Practical Aspects of Levin's Neutral Measure

Alexey Chernov

Computer Learning Research Centre and Department of Computer Science Royal Holloway University of London, UK

Marseille, 02.07.2009

Outline

Neutral Measures

Uniform Tests

Y is a metric compact, $\mathcal{P}(Y)$ is the set of all measures on Y

A lower semicontinuous function $t \colon Y \times \mathcal{P}(Y) \to \mathbb{R}$ is a uniform test if

$$\forall \mu \in \mathcal{P}(Y) \quad \int_{Y} t(y,\mu) d\mu(y) \leq 1$$

Uniform Tests

Y is a metric compact, $\mathcal{P}(Y)$ is the set of all measures on Y

A lower semicontinuous function $t \colon Y \times \mathcal{P}(Y) \to \mathbb{R}$ is a uniform test if

$$\forall \mu \in \mathcal{P}(Y) \quad \int_{Y} t(y,\mu) d\mu(y) \leq 1$$

Example:

Fix any measure ν on a finite set Y.

$$t(y,\mu) = \frac{\nu(y)}{\mu(y)}$$
 is a uniform test.



3/42

Neutral Measure

Theorem

Let $t(y, \mu)$ be a uniform test on metric compact Y. There exists a measure M on Y s.t.

$$\forall y \in Y \quad t(y,M) \leq 1$$
.

Neutral Measure

Theorem

Let $t(y, \mu)$ be a uniform test on metric compact Y. There exists a measure M on Y s.t.

$$\forall y \in Y \quad t(y, M) \leq 1$$
.

Neutral measure was introduced (with computability requirements) in:

Leonid Levin, "Uniform Tests of Randomness" (1976).

For details see: Peter Gács, "Lecture notes on descriptional complexity and randomness", Ch. 16.

We will ignore computability issues



Example: Neutral Measure on {0, 1}

$$Y = \{0, 1\}, P(Y) \cong [0, 1]: Prob(1) = p, Prob(0) = 1 - p$$

Let t(y, p) be lower semicontinuous in p and

$$\forall p \ \mathbf{E}_{p}t(y,p) = p t(1,p) + (1-p)t(0,p) \leq 1$$

There exists p s.t. $t(1,p) \le 1$ and $t(0,p) \le 1$.

Example: Neutral Measure on $\{0, 1\}$

$$Y = \{0, 1\}, P(Y) \cong [0, 1]: Prob(1) = p, Prob(0) = 1 - p$$

Let t(y, p) be lower semicontinuous in p and

$$\forall p \ \mathbf{E}_{p}t(y,p) = p t(1,p) + (1-p)t(0,p) \leq 1$$

There exists p s.t. $t(1,p) \le 1$ and $t(0,p) \le 1$.

Proof.

- $\{p \mid t(0,p) \le 1\} \cup \{p \mid t(1,p) \le 1\} = [0,1]$
- $0 \in \{p \mid t(0,p) \le 1\}$ and $1 \in \{p \mid t(1,p) \le 1\}$
- $\{p \mid t(0,p) \le 1\}$ and $\{p \mid t(1,p) \le 1\}$ are closed

Then
$$\{p \mid t(0,p) \le 1\} \cap \{p \mid t(1,p) \le 1\} \ne \emptyset$$



Outline

Neutral Measures

Probability Forecasting

Prediction with Expert Advice

Binary Betting Protocol

```
Initial capital of Skeptic \mathcal{K}_0=1
For n=1,2,\ldots
Forecaster announces p_n\in[0,1]
Skeptic buys s_n\in\mathbb{R} tickets
Reality announces y_n\in\{0,1\}
\mathcal{K}_n=\mathcal{K}_{n-1}+s_n(y_n-p_n)
```

Binary Betting Protocol

```
Initial capital of Skeptic \mathcal{K}_0 = 1
For n = 1, 2, ...
Forecaster announces p_n \in [0, 1]
Skeptic buys s_n \in \mathbb{R} tickets
Reality announces y_n \in \{0, 1\}
\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(y_n - p_n)
```

Goal: \mathcal{K}_n remains bounded. Forecaster plays against Skeptic and Reality.

Binary Betting Protocol

```
Initial capital of Skeptic K_0 = 1
For n = 1, 2, ...
```

Forecaster announces $p_n \in [0, 1]$

Skeptic buys $s_n \in \mathbb{R}$ tickets

Reality announces $y_n \in \{0, 1\}$

$$\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(y_n - p_n)$$

Goal: \mathcal{K}_n remains bounded.

Forecaster plays against Skeptic and Reality.

Generally unachievable: y_n s.t. $|y_n - p_n| \ge 0.5$, $s_n = \text{sign}(y_n - p_n)$.

Binary Defensive Forecasting Protocol

```
Initial capital of Skeptic \mathcal{K}_0 = 1
For n = 1, 2, ...
Skeptic announces s_n \colon [0, 1] \to \mathbb{R}
Forecaster announces p_n \in [0, 1]
Reality announces y_n \in \{0, 1\}
\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(p_n)(y_n - p_n)
```

Binary Defensive Forecasting Protocol

```
Initial capital of Skeptic \mathcal{K}_0 = 1

For n = 1, 2, ...

Skeptic announces continuous s_n \colon [0, 1] \to \mathbb{R}

Forecaster announces p_n \in [0, 1]

Reality announces y_n \in \{0, 1\}

\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(p_n)(y_n - p_n)
```

Binary Defensive Forecasting Protocol

```
Initial capital of Skeptic K_0 = 1
For n = 1, 2, ...
```

Skeptic announces continuous s_n : $[0,1] \to \mathbb{R}$

Forecaster announces $p_n \in [0, 1]$

Reality announces $y_n \in \{0, 1\}$

$$\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(p_n)(y_n - p_n)$$

Theorem

Forecaster has a strategy that guarantees $\mathcal{K}_0 \geq \mathcal{K}_1 \geq \mathcal{K}_2 \geq \dots$



Forecaster's Strategy

 s_n is continuous

$$\mathbf{E}_{p}s_{n}(p)(y-p) = ps_{n}(p)(1-p) + (1-p)s_{n}(p)(0-p) = 0$$

By the Neutral Measure Theorem, $\exists p \, \forall y \in \{0,1\} \ s_n(p)(y-p) \leq 0$ Thus $\mathcal{K}_n \leq \mathcal{K}_{n-1}$

Forecaster's Strategy

 s_n is continuous

$$\mathbf{E}_{p}s_{n}(p)(y-p) = ps_{n}(p)(1-p) + (1-p)s_{n}(p)(0-p) = 0$$

By the Neutral Measure Theorem, $\exists p \ \forall y \in \{0,1\} \ s_n(p)(y-p) \leq 0$ Thus $\mathcal{K}_n \leq \mathcal{K}_{n-1}$

Explicit algorithm:

- If $s_n(1) > 0$, take $p_n = 1$.
- If $s_n(0) < 0$, take $p_n = 0$.
- If $s_n(0) \ge 0$ and $s_n(1) \le 0$, take p_n s.t. $s_n(p_n) = 0$.

Thus $s_n(p_n)(y_n - p_n) \le 0$ for any $y_n \in \{0, 1\}$.



Uniformly Good Forecasts

```
For n = 1, 2, ...
```

Forecaster announces $p_n \in [0, 1]$

Reality announces $y_n \in \{0, 1\}$

Sceptic announces a continuous function $f: [0,1] \to \mathbb{R}$

Uniformly Good Forecasts

For n = 1, 2, ...

Forecaster announces $p_n \in [0, 1]$

Reality announces $y_n \in \{0, 1\}$

Sceptic announces a continuous function $f: [0,1] \to \mathbb{R}$

Forecaster's goal: $\sum_{n=1}^{N} f(p_n)(y_n - p_n)$ is small (grow slowly)

Calibration

 y_n is a Bernoulli sequence with Pr(1) = p

$$\frac{1}{N}\sum_{n=1}^{N}(y_n-p)\to 0$$

Calibration

 y_n is a Bernoulli sequence with Pr(1) = p

$$\frac{1}{N}\sum_{n=1}^{N}(y_n-p)\to 0$$

If p_n are different:

For each p take subsequence s.t. $p_n = p$

Calibration

 y_n is a Bernoulli sequence with Pr(1) = p

$$\frac{1}{N}\sum_{n=1}^{N}(y_n-p)\to 0$$

If p_n are different:

For each p take subsequence s.t. $p_n = p$

To get long (and frequently occurring) subsequences: $p_n \approx p$

$$\frac{1}{N}\sum_{n=1}^{N}\mathbb{I}_{p_n\approx p}(y_n-p_n)\to 0$$



Two Skeptics

Consider a simple version of uniformly good forecasting: a game with two Skeptics.

At step n, Skeptics buy $s_n^1(p_n)$ and $s_n^2(p_n)$ tickets, respectively.

Their capitals are $\mathcal{K}_n^i = \mathcal{K}_{n-1}^i + s_n^i(p_n)(y_n - p_n), i = 1, 2.$

Goal: both capitals remain small (grow slowly).

Two Skeptics

Consider a simple version of uniformly good forecasting: a game with two Skeptics.

At step n, Skeptics buy $s_n^1(p_n)$ and $s_n^2(p_n)$ tickets, respectively.

Their capitals are $\mathcal{K}_n^i = \mathcal{K}_{n-1}^i + s_n^i(p_n)(y_n - p_n), i = 1, 2.$

Goal: both capitals remain small (grow slowly).

Let
$$s_n = \begin{pmatrix} s_n^1 \\ s_n^2 \end{pmatrix}$$
, $\mathcal{K}_n = \begin{pmatrix} \mathcal{K}_n^1 \\ \mathcal{K}_n^2 \end{pmatrix}$.

$$\|\mathcal{K}_n\|^2 = (\mathcal{K}_n^1)^2 + (\mathcal{K}_n^2)^2.$$



Two Skeptics: Capital Bound

Initial capital of Skeptics
$$\mathcal{K}_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

For $n = 1, 2, ...$

Skeptic announces continuous s_n : $[0,1] \to \mathbb{R}^2$ Forecaster announces $p_n \in [0,1]$ Reality announces $y_n \in \{0,1\}$ $\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(p_n)(y_n - p_n)$

Two Skeptics: Capital Bound

Initial capital of Skeptics
$$\mathcal{K}_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

For $n = 1, 2, ...$

Skeptic announces continuous s_n : $[0,1] \to \mathbb{R}^2$ Forecaster announces $p_n \in [0,1]$ Reality announces $y_n \in \{0,1\}$ $\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(p_n)(y_n - p_n)$

Theorem

Forecaster has a strategy that guarantees

$$\|\mathcal{K}_n\| = \left\| \sum_{i=1}^n s_i(p_i)(y_i - p_i) \right\| \leq \sqrt{n} \max_i \max_{p \in [0,1]} \|s_i(p)\|$$



Two Skeptics: Forecaster's Strategy (1)

$$\begin{split} \|\mathcal{K}_{n}\|^{2} &= \left\| \sum_{i=1}^{n-1} s_{i}(\rho_{i})(y_{i} - \rho_{i}) + s_{n}(\rho_{n})(y_{n} - \rho_{n}) \right\|^{2} \\ &= \left\| \sum_{i=1}^{n-1} s_{i}(\rho_{i})(y_{i} - \rho_{i}) \right\|^{2} + \|s_{n}(\rho_{n})(y_{n} - \rho_{n})\|^{2} \\ &+ 2 \left\langle s_{n}(\rho_{n})(y_{n} - \rho_{n}), \sum_{i=1}^{n-1} s_{i}(\rho_{i})(y_{i} - \rho_{i}) \right\rangle \\ &= \|\mathcal{K}_{n-1}\|^{2} + \|s_{n}(\rho_{n})\|^{2} (y_{n} - \rho_{n})^{2} \\ &+ 2 \left\langle s_{n}(\rho_{n}), \sum_{i=1}^{n-1} s_{i}(\rho_{i})(y_{i} - \rho_{i}) \right\rangle (y_{n} - \rho_{n}) \end{split}$$

Two Skeptics: Forecaster's Strategy (2)

$$\begin{split} \|\mathcal{K}_n\|^2 &= \|\mathcal{K}_{n-1}\|^2 + \|s_n(p_n)\|^2 (y_n - p_n)^2 \\ &+ 2 \left\langle s_n(p_n), \sum_{i=1}^{n-1} s_i(p_i) (y_i - p_i) \right\rangle (y_n - p_n) \end{split}$$

By the Neutral Measure Theorem, we can take p_n s.t.

$$\left\langle s_n(p_n), \sum_{i=1}^{n-1} s_i(p_i)(y_i - p_i) \right\rangle (y_n - p_n) \leq 0$$

Two Skeptics: Forecaster's Strategy (2)

$$\begin{split} \|\mathcal{K}_n\|^2 &= \|\mathcal{K}_{n-1}\|^2 + \|s_n(p_n)\|^2 (y_n - p_n)^2 \\ &+ 2 \left\langle s_n(p_n), \sum_{i=1}^{n-1} s_i(p_i) (y_i - p_i) \right\rangle (y_n - p_n) \end{split}$$

By the Neutral Measure Theorem, we can take p_n s.t.

$$\left\langle s_n(p_n), \sum_{i=1}^{n-1} s_i(p_i)(y_i-p_i) \right\rangle (y_n-p_n) \leq 0$$

Thus,
$$\|\mathcal{K}_n\|^2 \le \|\mathcal{K}_{n-1}\|^2 + \|s_n(p_n)\|^2$$

Finally, $\|\mathcal{K}_n\|^2 \le n \max_i \max_{p \in [0,1]} \|s_i(p)\|^2$



Two Skeptics: Linear Mixtures

Corollary

The Forecaster strategy above guarantees also that for any

$$\alpha = (\alpha_1, \alpha_2) \in \mathbb{R}^2$$

$$|\alpha_1 \mathcal{K}_n^1 + \alpha_2 \mathcal{K}_n^2| \le \sqrt{n} \|\alpha\| \max_i \max_{p \in [0,1]} \|s_i(p)\|$$

Two Skeptics: Linear Mixtures

Corollary

The Forecaster strategy above guarantees also that for any

$$\alpha = (\alpha_1, \alpha_2) \in \mathbb{R}^2$$

$$|\alpha_1 \mathcal{K}_n^1 + \alpha_2 \mathcal{K}_n^2| \leq \sqrt{n} \, \|\alpha\| \max_i \max_{p \in [0,1]} \|s_i(p)\|$$

Proof.

$$|\alpha_1 \mathcal{K}_n^1 + \alpha_2 \mathcal{K}_n^2| = |\langle \alpha, \mathcal{K}_n \rangle| \le ||\alpha|| ||\mathcal{K}_n||$$



Skeptic with values in Hilbert Space

```
\mathcal{H} is any Hilbert space
For n = 1, 2, ...
```

Skeptic announces continuous s_n : $[0,1] \to \mathcal{H}$ Forecaster announces $p_n \in [0,1]$ Reality announces $y_n \in \{0,1\}$ $\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(p_n)(y_n - p_n)$

Skeptic with values in Hilbert Space

 \mathcal{H} is any Hilbert space For n = 1, 2, ...

> Skeptic announces continuous $s_n \colon [0,1] \to \mathcal{H}$ Forecaster announces $p_n \in [0,1]$ Reality announces $y_n \in \{0,1\}$ $\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(p_n)(y_n - p_n)$

Theorem

Forecaster has a strategy that guarantees for any $\alpha \in \mathcal{H}$

$$\left|\left\langle \alpha, \sum_{i=1}^{n} s_{i}(p_{i})(y_{i} - p_{i}) \right\rangle \right| \leq \sqrt{n} \|\alpha\|_{\mathcal{H}} \max_{i} \max_{p \in [0,1]} \|s_{i}(p)\|_{\mathcal{H}}$$

- ◆ロト ◆御 ト ◆恵 ト ◆恵 ト ・恵 ・ 夕久(^)

Skeptic with values in Hilbert Space

 \mathcal{H} is any Hilbert space, X is a metric compact For n = 1, 2, ...

Reality announces $x_n \in X$

Skeptic announces continuous $s_n \colon X \times [0,1] \to \mathcal{H}$

Forecaster announces $p_n \in [0, 1]$

Reality announces $y_n \in \{0, 1\}$

$$\mathcal{K}_n = \mathcal{K}_{n-1} + s_n(x_n, p_n)(y_n - p_n)$$

Theorem

Forecaster has a strategy that guarantees for any $\alpha \in \mathcal{H}$

$$\left|\left\langle \alpha, \sum_{i=1}^{n} s_i(x_i, p_i)(y_i - p_i) \right\rangle \right| \leq \sqrt{n} \|\alpha\|_{\mathcal{H}} \max_{i} \max_{(x, p) \in X \times [0, 1]} \|s_i(x, p)\|_{\mathcal{H}}$$

4 □ ト 4 同 ト 4 亘 ト 4 亘 ・ 夕 Q ○

Reproducing Kernel Hilbert Spaces

Let \mathcal{F} be a Hilbert Space of functions $X \to \mathbb{R}$

Requirement: $||f|| \approx 0 \quad \Rightarrow \quad \forall x \, |f(x)| \approx 0$

Reproducing Kernel Hilbert Spaces

Let \mathcal{F} be a Hilbert Space of functions $X \to \mathbb{R}$

Requirement: $||f|| \approx 0 \quad \Rightarrow \quad \forall x \, |f(x)| \approx 0$

 \mathcal{F} is a reproducing kernel Hilbert space on X iff for any $x \in X$ there exists $\mathbf{k}_x \in \mathcal{F}$ s.t.

$$f(x) = \langle \mathbf{k}_{x}, f \rangle, \forall f \in \mathcal{F}$$

Reproducing Kernel Hilbert Spaces

Let \mathcal{F} be a Hilbert Space of functions $X \to \mathbb{R}$

Requirement: $||f|| \approx 0 \quad \Rightarrow \quad \forall x \, |f(x)| \approx 0$

 \mathcal{F} is a reproducing kernel Hilbert space on X iff for any $x \in X$ there exists $\mathbf{k}_x \in \mathcal{F}$ s.t.

$$f(x) = \langle \mathbf{k}_{x}, f \rangle, \forall f \in \mathcal{F}$$

Example:

$$f: [0,1] \to \mathbb{R} \text{ s.t. } f(0) = 0$$

 $\langle f, g \rangle = \int_0^1 f'(x)g'(x)dx$

$$\mathbf{k}_{x}(z) = \begin{cases} z, z \leq x \\ x, z > x \end{cases}$$



RKHS-Assessed Probability Forecasts

```
X is metric compact
For n = 1, 2, ...
```

Reality announces $x_n \in X$

Forecaster announces $p_n \in [0, 1]$

Reality announces $y_n \in \{0, 1\}$

RKHS-Assessed Probability Forecasts

X is metric compact For n = 1, 2, ...

Reality announces $x_n \in X$

Forecaster announces $p_n \in [0, 1]$

Reality announces $y_n \in \{0, 1\}$

Theorem

Let \mathcal{F} be an RKHS on $X \times [0,1]$ s.t. $\mathbf{k}_{x,p}$ is continuous in x,p and $C_{\mathcal{F}} = \sup_{x,p} \sup_{\|g\|_{\mathcal{F}}=1} g(x,p)$.

Forecaster has a strategy for $\mathcal F$ s.t. for any $f \in \mathcal F$

$$\left|\sum_{n=1}^N f(x_n, p_n)(y_n - p_n)\right| \leq C_{\mathcal{F}} \|f\|_{\mathcal{F}} \sqrt{N}$$



RKHS-Assessed Forecasts: Proof

Take "Hilbert-valued" Sceptic

$$s_n(x_n,p_n)=\mathbf{k}_{x_n,p_n}$$

Forecaster can guarantee that for any $f \in \mathcal{F}$

$$\left|\sum_{n=1}^{N} \left\langle f, \mathbf{k}_{x_n, p_n} \right\rangle (y_n - p_n) \right| \leq \sqrt{N} \|f\|_{\mathcal{F}} \max_{(x, p) \in X \times [0, 1]} \|\mathbf{k}_{x, p}\|_{\mathcal{F}}$$

$$\langle f, \mathbf{k}_{x_n, p_n} \rangle = f(x_n, p_n)$$
 for any $f \in \mathcal{F}$.

$$\|\mathbf{k}_{x,p}\|_{\mathcal{F}} \leq C_{\mathcal{F}}$$

General Asymptotic Calibration

X and Y are compact metric spaces For n = 1, 2, ...

> Reality announces $x_n \in X$ Forecaster announces $P_n \in \mathcal{P}(Y)$ Reality announces $y_n \in Y$

General Asymptotic Calibration

X and Y are compact metric spaces For n = 1, 2, ...

Reality announces $x_n \in X$

Forecaster announces $P_n \in \mathcal{P}(Y)$

Reality announces $y_n \in Y$

Theorem

Forecaster has a strategy s.t. for any continuous $f: X \times \mathcal{P}(Y) \times Y \to \mathbb{R}$

$$\lim_{N\to\infty}\frac{1}{N}\sum_{n=1}^N\left(f(x_n,P_n,y_n)-\int_Yf(x_n,P_n,y)P_n(dy)\right)=0$$



Function Approximation

X is metric compact, B > 0 For n = 1, 2, ...

Reality announces $x_n \in X$

Forecaster announces $\gamma_n \in [-B, B]$

Reality announces $y_n \in [-B, B]$

Function Approximation

X is metric compact, B > 0For n = 1, 2, ...

Reality announces $x_n \in X$

Forecaster announces $\gamma_n \in [-B, B]$

Reality announces $y_n \in [-B, B]$

Theorem

Let \mathcal{F} be an RKHS on X.

Forecaster has a strategy that guarantees for any $f \in \mathcal{F}$

$$\sum_{n=1}^{N} (y_n - \gamma_n)^2 \leq \sum_{n=1}^{N} (y_n - f(x_n))^2 + O(B^2 ||f||_{\mathcal{F}} \sqrt{N})$$



References

Results by Volodya Vovk, some in coauthorship with Ilia Nouretdinov, Glenn Shafer, and Akimichi Takemura.

Recent experimental results by Brian Burford, Fedor Zhdanov.

For more details, see

```
http://onlineprediction.net/
http://vovk.net/df/index.html
```

Outline

Neutral Measures

Probability Forecasting

Prediction with Expert Advice

	Prediction	
Expert 1	π^1	
:	:	
Expert K	π^{K}	
Learner		

	Prediction	
Expert 1	π^{1}	
<u>:</u>	i	
Expert K	π^{K}	
Learner	π	

	Prediction	Loss
Expert 1	π^{1}	$\lambda(\pi^1,\omega)$
:	i i	:
Expert K	π^{K}	$\lambda(\pi^K,\omega)$
Learner	π	$\lambda(\pi,\omega)$

 ω is the outcome

Goal: Learner's loss is not greater than the loss of any Expert

	Prediction	Loss
Expert 1	π^{1}	$\lambda(\pi^1,\omega)$
:	i	:
Expert K	π^{K}	$\lambda(\pi^K,\omega)$
Learner	π	$\lambda(\pi,\omega)$

 ω is the outcome

Goal: Learner's loss is not greater than the loss of any Expert

At each step N, for any k,

$$\sum_{n=1}^{N} \lambda(\pi_n, \omega_n) \leq \sum_{n=1}^{N} \lambda(\pi_n^k, \omega_n) + \text{something small}$$

Prediction with Expert Advice: Protocol

Outcome space Ω , $|\Omega| < \infty$.

Experts 1, 2, ... (finitely or infinitely many)

Loss function $\lambda \colon \mathcal{P}(\Omega) \times \Omega \to [0, \infty]$

$$L_0^k = 0, L_0 = 0$$

For $n = 1, 2, ...$

Experts announce $\pi_n^k \in \mathcal{P}(\Omega)$.

Learner announces $\pi_n \in \mathcal{P}(\Omega)$.

Reality announces $\omega_n \in \Omega$.

$$L_n^k = L_{n-1}^k + \lambda(\pi_n^k, \omega_n), \quad L_n = L_{n-1} + \lambda(\pi_n, \omega_n).$$

One can consider non-probabilistic predictions as well.



Prediction with Expert Advice: Protocol

Outcome space Ω , $|\Omega| < \infty$.

Experts 1, 2, ... (finitely or infinitely many)

Loss function $\lambda \colon \mathcal{P}(\Omega) \times \Omega \to [0, \infty]$

$$L_0^k = 0, L_0 = 0$$

For $n = 1, 2, ...$

Experts announce $\pi_n^k \in \mathcal{P}(\Omega)$.

Learner announces $\pi_n \in \mathcal{P}(\Omega)$.

Reality announces $\omega_n \in \Omega$.

$$L_n^k = L_{n-1}^k + \lambda(\pi_n^k, \omega_n), \quad L_n = L_{n-1} + \lambda(\pi_n, \omega_n).$$

Learner plays against Experts and Reality.

Goal: $L_n \leq L_n^k + Const(k)$, for all k and n.

One can consider non-probabilistic predictions as well.



Prediction with Expert Advice: Bound

Theorem

Let w^k be arbitrary weights of Experts, $w^k \ge 0$, $\sum w^k \le 1$. If λ is η -mixable, then Learner has a strategy that guarantees for all n and for all k that

$$L_n \leq L_n^k + \frac{1}{\eta} \ln \frac{1}{w^k} .$$

The bound is in a sense optimal.

 λ is η-mixable iff for any $\pi^k \in \mathcal{P}(\Omega)$ and any weights w^k

$$\exists \pi \in \mathcal{P}(\Omega) \ \forall \omega \quad e^{-\eta \lambda(\pi,\omega)} \ge \sum_{k=1}^K \mathbf{w}^k e^{-\eta \lambda(\pi^k,\omega)}.$$



Example: Log Loss

Logarithmic loss:

$$\lambda(\pi,\omega) = \ln \frac{1}{\pi(\omega)}$$

Log loss is 1-mixable

Example: Log Loss

Logarithmic loss:

$$\lambda(\pi,\omega) = \ln \frac{1}{\pi(\omega)}$$

Log loss is 1-mixable

Let
$$\mu^k(\omega_n|\omega_1\ldots\omega_{n-1})=\pi_n^k(\omega_n)$$
, $M(\omega_n|\omega_1\ldots\omega_{n-1})=\pi_n(\omega_n)$.
Then $L_N^k=\sum_{n=1}^N\ln\frac{1}{\pi_n^k(\omega_n)}=\ln\frac{1}{\mu^k(\omega_1\ldots\omega_N)}$, $L_N=\ln\frac{1}{M(\omega_1\ldots\omega_N)}$ and the bound of the theorem reduces to

$$\mu^k(\omega_1\ldots\omega_N)\leq \frac{1}{w^k}M(\omega_1\ldots\omega_N)$$

Example: Square (Brier) Loss

Square (Brier) loss:

$$\lambda(\pi,\omega) = (1-\pi(\omega))^2 + \sum_{\omega' \neq \omega} (\pi(\omega'))^2$$

Also 1-mixable

For
$$\Omega = \{0, 1\}, \quad \lambda(\pi, \omega) = 2(1 - \pi(\omega))^2$$

$$2\sum_{n=1}^{N}(1-M(\omega_{n}|\omega_{1}\ldots\omega_{n-1}))^{2}\leq 2\sum_{n=1}^{N}(1-\mu^{k}(\omega_{n}|\omega_{1}\ldots\omega_{n-1}))^{2}+\ln\frac{1}{w^{k}}$$

Real Bookmakers

Recent experiments by Fedor Zhdanov.

Data:

4 bookmakers, odds for \sim 10000 tennis matches (2 outcomes)

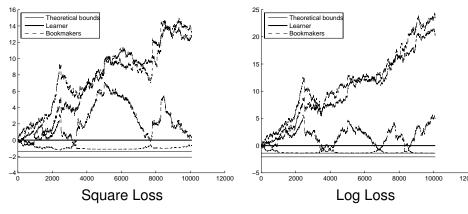
8 bookmakers, odds for \sim 9000 football matches (3 outcomes)

Odds can be transformed to probabilities

There is no obvious choice for the loss function Use just two popular losses: log loss and square loss

Tennis Odds: "Own" Loss

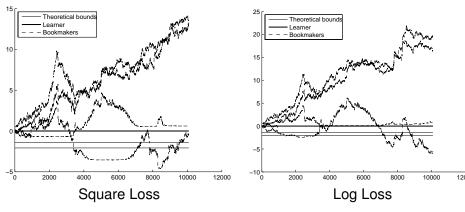
Graphs of the regret $L_n^k - L_n$ ($\geq -\ln 4$, theoretically)



Learner optimizes for the same loss function

Tennis Odds: "Foreign" Loss

Graphs of the regret $L_n^k - L_n$ (no theoretical bound)



Learner optimizes for the other loss function

Multiobjective PEA: Scheme

	Prediction	Loss
Expert 1	π^1	$\lambda^{1}(\pi^{1},\omega),\ldots,\lambda^{M}(\pi^{1},\omega)$
:	:	:
Expert K	π^{K}	$\lambda^{1}(\pi^{K},\omega),\ldots,\lambda^{M}(\pi^{K},\omega)$
Learner	π	$\lambda^{1}(\pi,\omega),\ldots,\lambda^{M}(\pi,\omega)$

$$\begin{split} \sum_{n=1}^N \lambda^1(\pi_n,\omega_n) &\leq \sum_{n=1}^N \lambda^1(\pi_n^k,\omega_n) + \text{something small} \\ &\vdots \\ \sum_{n=1}^N \lambda^M(\pi_n,\omega_n) &\leq \sum_{n=1}^N \lambda^M(\pi_n^k,\omega_n) + \text{something small} \end{split}$$

Multiobjective PEA: Protocol

Outcome space Ω , $|\Omega| < \infty$.

Experts 1, 2, 3, ... (finitely or infinitely many)

Loss functions
$$\lambda^1 \colon \mathcal{P}(\Omega) \times \Omega \to [0,\infty], \ \lambda^2 \colon \mathcal{P}(\Omega) \times \Omega \to [0,\infty], \dots$$

$$L_0^{k,m} = 0, L_0^m = 0$$

For $n = 1, 2, ...$

Experts announce $\pi_n^k \in \mathcal{P}(\Omega)$.

Learner announces $\pi_n \in \mathcal{P}(\Omega)$.

Reality announces $\omega_n \in \Omega$.

$$L_n^{k,m} = L_{n-1}^{k,m} + \lambda^m(\pi_n^k, \omega_n), \quad L_n^m = L_{n-1}^m + \lambda^m(\pi_n, \omega_n).$$

Learner plays against Experts and Reality.

Goal: $L_n^m \leq L_n^{k,m} + Const(k,m)$, for all k, m and n.



Multiobjective PEA: Bound

Theorem

Let $w^{k,m}$ be arbitrary weights of Experts and loss functions, $w^{k,m} \ge 0$, $\sum w^{k,m} < 1$.

If each λ^m is η^m -mixable and strictly proper, then Learner has a strategy that guarantees for all n and for all k and m that

$$L_n^m \leq L_n^{k,m} + \frac{1}{\eta^m} \ln \frac{1}{w^{k,m}}.$$

Multiobjective PEA: Bound

Theorem

Let $w^{k,m}$ be arbitrary weights of Experts and loss functions, $w^{k,m} \ge 0$, $\sum w^{k,m} < 1$.

If each λ^m is η^m -mixable and strictly proper, then Learner has a strategy that guarantees for all n and for all k and m that

$$L_n^m \leq L_n^{k,m} + \frac{1}{\eta^m} \ln \frac{1}{w^{k,m}}$$
.

Strictly Proper Loss Functions

 λ is proper if for any $\pi, \pi' \in \mathcal{P}(\Omega)$, $\pi \neq \pi'$

$$\mathbf{E}_{\pi}\lambda(\pi,\omega) < \mathbf{E}_{\pi}\lambda(\pi',\omega)$$
, where $\mathbf{E}_{\pi}\lambda(\pi',\omega) = \sum_{\omega} \pi(\omega)\lambda(\pi,\omega)$

Motivation:

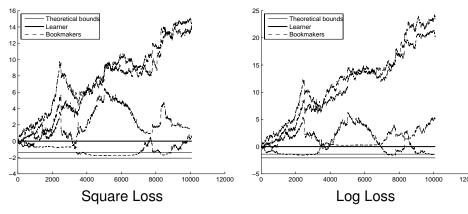
if $\omega \sim \pi$ then $\mathbf{E}_{\pi}\lambda(\pi',\omega)$ is the expected loss for prediction π' .

A proper loss function encourages to predict the true probability distribution

⇒ predictions are really (not formally) probabilistic

Tennis Odds: Two Losses

Graphs of the regret $L_n^k - L_n$ ($\geq -\ln 8$, theoretically)



Learner optimizes for both loss functions

Multiobjective PEA: Proof Idea

Lemma

If λ is strictly proper and η -mixable, then $\lambda(\pi,\omega)$ is a continuous function of π and for any $\pi,\pi'\in\mathcal{P}(\Omega)$

$$\textbf{E}_{\pi} \frac{\mathrm{e}^{\eta \lambda(\pi,\omega)}}{\mathrm{e}^{\eta \lambda(\pi',\omega)}} = \sum_{\omega} \pi(\omega) \frac{\mathrm{e}^{\eta \lambda(\pi,\omega)}}{\mathrm{e}^{\eta \lambda(\pi',\omega)}} \leq 1 \ .$$

Example: for log loss $\lambda(\pi,\omega) = \ln \frac{1}{\pi(\omega)}$, $\eta = 1$,

$$\sum_{\omega} \pi(\omega) \frac{e^{\lambda(\pi,\omega)}}{e^{\lambda(\pi',\omega)}} = \sum_{\omega} \pi(\omega) \frac{\frac{1}{\pi(\omega)}}{\frac{1}{\pi'(\omega)}} = \sum_{\omega} \pi'(\omega) = 1$$



Multiobjective PEA: Algorithm

At step *N*:

$$f_{N}(\pi,\omega) = \sum_{k,m} \left(\mathbf{w}^{k,m} \prod_{n=1}^{N-1} \frac{e^{\eta^{m} \lambda^{m}(\pi_{n},\omega_{n})}}{e^{\eta^{m} \lambda^{m}(\pi_{n}^{k},\omega_{n})}} \right) \frac{e^{\eta^{m} \lambda^{m}(\pi,\omega)}}{e^{\eta^{m} \lambda^{m}(\pi_{N}^{k},\omega)}}$$

Find $\pi \in \mathcal{P}(\Omega)$ s.t.

$$f_N(\pi,\omega) \leq 1$$

for all ω .

 π exists by the Neutral Measure Theorem.

Learner predicts $\pi_N = \pi$.

Multiobjective PEA: Proof of the Bound

For any N,

$$\sum_{k,m} \left(w^{k,m} \prod_{n=1}^N \frac{\mathrm{e}^{\eta^m \lambda^m (\pi_n,\omega_n)}}{\mathrm{e}^{\eta^m \lambda^m (\pi_n^k,\omega_n)}} \right) \leq 1 \ .$$

Thus,

$$\frac{e^{\sum_{n=1}^N \eta^m \lambda^m (\pi_n, \omega_n)}}{e^{\sum_{n=1}^N \eta^m \lambda^m (\pi_n^k, \omega_n)}} \leq \frac{1}{w^{k,m}}.$$

Finally,

$$L_N^m \leq L_N^{k,m} + \ln \frac{1}{w^{k,m}}$$

Possible Future Work

For any measures μ^k , we can (non-constructively) find a (non-computable) measure M s.t.

$$\mu^k(\omega_1\ldots\omega_N)\leq \frac{1}{w^k}M(\omega_1\ldots\omega_N)$$

and

$$\sum_{n=1}^{N} (1 - M(\omega_n | \omega_1 \dots \omega_{n-1}))^2 \le \sum_{n=1}^{N} (1 - \mu^k (\omega_n | \omega_1 \dots \omega_{n-1}))^2 + \frac{1}{2} \ln \frac{1}{w^k}$$

Is it possible to find a semi-enumerable M for all computable μ ?



References

For more details, see

http://onlineprediction.net/

A. Chernov, Y. Kalnishkan, F. Zhdanov, V. Vovk. Supermartingales in Prediction with Expert Advice. ALT 2008.

A. Chernov, V. Vovk. Prediction with expert evaluators' advice.

http://arxiv.org/abs/0902.4127