

Approximation Semantics and Expressive Predicate Assignment for Object-Oriented Programming

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Summary

We study FJ^ϕ , Featherweight Java without casts.

FJ is a restriction of Java defined by removing all but the most essential features of the full language; FJ bears a similar relation to **Java** as the λ -calculus does to languages such as **ML** and **Haskell**.

We study two semantics for FJ:

- An *approximation* model;
- An *(intersection) type-based* model.

We define these because we want to define *semantics-based systems* of *abstract interpretation* for Java.

We will (in future work) extend FJ^ϕ with the usual (imperative) features, working towards **Java**.

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1. The function $\mathcal{F}(C)$ returns the list of fields \vec{f}_n belonging to class C (including those it inherits).
2. The function $\mathcal{M}b(C, m)$ returns a tuple (\vec{x}, e) , consisting of a sequence of the method m 's formal parameters and its body (as present in the class C).

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 - $\text{new } C(\vec{e}_n).f_i \rightarrow e_i$, for class name C with $\mathcal{F}(C) = \vec{f}_n$ and $i \in \bar{n}$.
 - $\text{new } C(\vec{e}).m(\vec{e}'_n) \rightarrow e^S$, where $S = \{\text{this} \mapsto \text{new } C(\vec{e}), x_1 \mapsto e'_1, \dots, x_n \mapsto e'_n\}$, for class name C and method m with $\mathcal{M}b(C, m) = (\vec{x}_n, e)$.

This notion of reduction is *confluent*.

Approximants for FJ^ϕ

Following the standard concept, we define the notion of approximant for FJ^ϕ by replacing *(possibly) active computations* in expressions with \perp .

The set of *approximate normal forms*, \underline{A} , ranged over by A , is defined by the following grammar (extending expressions with \perp):

$$\begin{aligned} A ::= & x \mid \text{this} \mid \perp \mid \text{new } C(\vec{A}_n) \quad (n \geq 0) \\ & \mid A.f \mid A.m(\vec{A}) \quad (A \neq \perp, A \neq \text{new } C(\vec{A}_n)) \end{aligned}$$

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We consider $\perp.f$ not in normal form: it can be that \perp hides an expression that reduces to an object $\text{new } C(\vec{A}_n)$, in which case the field invocation can run, so disappears.

Approximation Semantics

The *approximation relation* \sqsubseteq is an order on terms defined by taking \perp to be smaller (i.e. containing less information) than any other term, and by extending this to a relation between all terms:

$$\begin{array}{l} \perp \sqsubseteq A \\ A \sqsubseteq A' \ \& \ \forall i \leq n \ A_i \sqsubseteq A'_i \end{array} \Rightarrow \left\{ \begin{array}{ll} A.f & \sqsubseteq A'.f \\ \text{new } C(\vec{A}_n) & \sqsubseteq \text{new } C(\vec{A}'_n) \\ A.m(\vec{A}_n) & \sqsubseteq A'.m(\vec{A}'_n) \end{array} \right.$$

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We define the set of *approximants* of e as $\mathcal{A}(e) = \{ A \mid \exists e' [e \rightarrow^* e' \ \& \ A \sqsubseteq e'] \}$.

We can show: $e \rightarrow^* e' \Rightarrow \mathcal{A}(e) = \mathcal{A}(e')$.

This result allows us to define a semantics for FJ^ζ by interpreting expressions by the set of their approximants: $\llbracket e \rrbracket = \mathcal{A}(e)$.

Predicates (vs. Java types)

Our predicates describe the capabilities of an expression in terms of

1. the *operations* that may be performed on it (i.e. accessing a field or invoking a method), and
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$$\phi, \psi ::= \omega \mid \sigma \mid \phi \cap \psi$$

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The *predicate assignment* relation is expressed through the standard notation $\Pi \vdash e : \phi$, where as usual Π contains type assumptions for the variables in e .

It is defined by ...

The Derivation Rules

$$(\text{VAR}) : \frac{}{\Pi, x:\phi \vdash x:\sigma} (\phi \trianglelefteq \sigma) \quad (\text{FLD}) : \frac{\Pi \vdash e:\langle f:\sigma \rangle}{\Pi \vdash e.f:\sigma}$$

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 (\text{INVK}) : \frac{\Pi \vdash e:\langle m:(\phi_1, \dots, \phi_n) \rightarrow \sigma \rangle \quad \Pi \vdash e_1:\phi_1 \dots \Pi \vdash e_n:\phi_n}{\Pi \vdash e.m(\vec{e}_n):\sigma} \\
 (\text{NEWO}) : \frac{\Pi \vdash e_1:\phi_1 \quad \dots \quad \Pi \vdash e_n:\phi_n}{\Pi \vdash \text{new } C(\vec{e}_n):C} \quad (\mathcal{F}(C) = \vec{f}_n) \\
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 (\text{NEWM}) : \frac{\text{this}:\psi, \vec{x}:\vec{\phi}_n \vdash e_b:\sigma \quad \Pi \vdash \text{new } C(\vec{e}):\psi}{\Pi \vdash \text{new } C(\vec{e}):\langle m:(\vec{\phi}_n) \rightarrow \sigma \rangle} \quad (\mathcal{M}b(C, m) = (\vec{x}_n, e_b))
 \end{array}$$

We show: if $e \rightarrow e'$ then $\Pi \vdash e':\phi \Leftrightarrow \Pi \vdash e:\phi$; this gives a type-based semantics.

The Approximation Result

We now have two approaches to semantics: (1) the approximation model, and (2) a type based semantics. So what is the relation between the two?

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- If an expression e can be given a predicate ϕ , then there exists an approximant A of e that has the same predicate. i.e: if we run e long enough, a stable result will appear (with perhaps computations still going on inside) that has the same predicate ϕ : predicates ‘foretell’ the shape of the result.

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The proof for this property is not straightforward; the main problem is that reduction in FJ^{ϕ} is *weak*. To solve it, we use a notion of *derivation reduction* that follows reduction of expressions on, but reduces only those that do not have predicate ω .

Derivation Reduction

$$\frac{\frac{\boxed{\mathcal{D}_1} \quad \boxed{\mathcal{D}_n}}{\Pi \vdash e_1 : \phi_1 \quad \dots \quad \Pi \vdash e_n : \phi_n}}{\Pi \vdash \text{new } C(\vec{e}_n) : \langle f_i : \sigma \rangle}}{\Pi \vdash \text{new } C(\vec{e}_n).f_i : \sigma} \rightarrow_{\mathfrak{D}} \frac{\boxed{\mathcal{D}_i}}{\Pi \vdash e_i : \sigma}$$

Notice that $\text{new } C(\vec{e}_n).f_i \rightarrow e_i$. We also contract:

$$\frac{\frac{\boxed{\mathcal{D}_b} \quad \boxed{\mathcal{D}_{\text{self}}}}{\text{this} : \psi, x_1 : \phi_1, \dots, x_n : \phi_n \vdash e_b : \sigma \quad \Pi \vdash \text{new } C(\vec{e}_n) : \psi}}{\Pi \vdash \text{new } C(\vec{e}_n) : \langle m : (\vec{\phi}_n) \rightarrow \sigma \rangle}}{\frac{\begin{array}{c} \vdots \\ \boxed{\mathcal{D}_1} \quad \boxed{\mathcal{D}_n} \\ \vdots \quad \Pi \vdash e_1 : \phi_1 \quad \dots \quad \Pi \vdash e_n : \phi_n \end{array}}{\Pi \vdash \text{new } C(\vec{e}).m(\vec{e}_n) : \sigma}} \rightarrow_{\mathfrak{D}} \frac{\boxed{\mathcal{D}_b^S}}{\Pi \vdash e_b^S : \sigma}$$

and $\text{new } C(\vec{e}).m(\vec{e}_n) \rightarrow e_b$, where $\text{D } m(\vec{E} \ x_n) \{ \text{return } e_b ; \}$ is present in C .

Derivation Reduction is Strongly Normalising

First we show that derivation reduction is sound: If $\mathcal{D} :: \Pi \vdash e : \phi$ and $\mathcal{D} \rightarrow_{\mathcal{D}} \mathcal{D}'$, then \mathcal{D}' is a well-defined derivation, in that is there exists some e' such that $\mathcal{D}' :: \Pi \vdash e' : \phi$, and $e \rightarrow e'$.

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We show that all reductions on derivations *terminate*.

$$\mathcal{D} :: \Pi \vdash e : \phi \Rightarrow \text{SN}(\mathcal{D}).$$

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In fact, if ω has been used in \mathcal{D} , then all executions inside the expression that has this predicate are *invisible* and will not be executed when reducing the derivation.

So in the normal form of a derivation, the expression involved need not be in normal form.

The proof for this property is not straightforward, since typeable terms need not terminate - we use the *computability* technique (Tait).

Main results

From the termination result for derivation reduction, these others follow:

Approximation result: $\Pi \vdash e : \phi \Leftrightarrow \exists A \in \mathcal{A}(e) [\Pi \vdash A : \phi]$.

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Normalisation: $\mathcal{D} :: \Pi \vdash e : \sigma$ with ω -safe \mathcal{D} and Π only if e has a *normal form*.

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Strong Normalisation: $\mathcal{D} :: \Pi \vdash e : \sigma$ with \mathcal{D} strong if and only if e is *strongly normalisable*.

If ω is *not used at all* in \mathcal{D} , then *all* executions of e will produce a result.

Expressivity

We compare our work to previous results (and show that FJ^ϕ is Turing complete) by considering an encoding of the **SK** Combinatory Logic (**CL**) in FJ^ϕ :

$$\mathbf{K} \ x \ y \ \rightarrow \ x$$

$$\mathbf{S} \ x \ y \ z \ \rightarrow \ x \ z \ (y \ z)$$

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The encoding of **CL** into the FJ^ϕ program **ooCL** (Object-Oriented **CL**) is defined using the class table on the next slide and the function $\llbracket \cdot \rrbracket$ which translates terms of **CL** into FJ^ϕ expressions, and is defined as follows:

$$\llbracket x \rrbracket = x \qquad \llbracket t_1 t_2 \rrbracket = \llbracket t_1 \rrbracket . \text{app}(\llbracket t_2 \rrbracket)$$

$$\llbracket \mathbf{K} \rrbracket = \text{new } K_0() \qquad \llbracket \mathbf{S} \rrbracket = \text{new } S_0()$$

If $t_1 \rightarrow t_2$ in **CL**, then $\llbracket t_1 \rrbracket \rightarrow \llbracket t_2 \rrbracket$ in FJ^ϕ .

OOCL

```
class Combinator extends Object {
    Combinator app(Combinator x) { return this; } }

class K0 extends Combinator {
    Combinator app(Combinator x) { return new K1(x); } }

class K1 extends K0 { Combinator x;
    Combinator app(Combinator y) { return this.x; } }

class S0 extends Combinator {
    Combinator app(Combinator x) { return new S1(x); } }

class S1 extends S0 { Combinator x;
    Combinator app(Combinator y) { return new S2(this.x, y); } }

class S2 extends S1 { Combinator y;
    Combinator app(Combinator z) {
        return this.x.app(z).app(this.y.app(z)); } }
```

Type preservation

The set of *simple types* is defined by $\tau ::= \varphi \mid \tau \rightarrow \tau$. The *basis* B contains type assumptions for variables. Simple types are assigned to CL-terms using:

$$\begin{array}{l} (\text{VAR}) : \frac{}{B \vdash_{\text{CL}} x:\tau} \quad (x:\tau \in B) \quad (\rightarrow\text{E}) : \frac{B \vdash_{\text{CL}} t_1:\tau \rightarrow \tau' \quad B \vdash_{\text{CL}} t_2:\tau}{B \vdash_{\text{CL}} t_1 t_2:\tau'} \\ (\text{K}) : \frac{}{B \vdash_{\text{CL}} K:\tau \rightarrow \tau' \rightarrow \tau} \quad (\text{S}) : \frac{}{B \vdash_{\text{CL}} S:(\tau \rightarrow \tau' \rightarrow \tau'') \rightarrow (\tau \rightarrow \tau') \rightarrow \tau \rightarrow \tau''} \end{array}$$

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We define what the equivalent of Curry's types are in terms of predicates.

$$\begin{aligned} \llbracket \varphi \rrbracket &= \varphi \\ \llbracket \tau \rightarrow \tau' \rrbracket &= \langle \text{app} : \llbracket \tau \rrbracket \rightarrow \llbracket \tau' \rrbracket \rangle \end{aligned}$$

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Then we can show: If $\mathbf{B} \vdash_{\text{CL}} t:\tau$ then $\llbracket \mathbf{B} \rrbracket \vdash \llbracket t \rrbracket : \llbracket \tau \rrbracket$.

Let $e = \llbracket t \rrbracket$ for some **CL** term t ; then e has a normal form if and only if there are ω -safe \mathbf{D} and $\mathbf{\Pi}$ and predicate σ such that $\mathbf{D} :: \mathbf{\Pi} \vdash e:\sigma$.

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Conclusions

We have defined two different semantics for a (kernel) class-based object oriented programming language FJ^ϕ , and stated how they relate.

We have proven all important properties for predicate assignment. Through our predicate assignment system, we can characterise

- *Head normalisation.*
- *Normalisation.*
- *Strong normalisation.*

We have shown that FJ^ϕ is *fully expressive*, by mapping CL into $OOCL$ (we could even map the λ -calculus).

As a first exercise of how ‘handy’ our system is, we have shown that all (simply) typeable $OOCL$ programs terminate, and vice-versa.

Approximants (concept)

An *approximant* is a (finite) description of the result of the running of a program that will not change (the output) while the program still runs. We hide a place where computation takes place with \perp ; we see \perp as representing “*No information on the computation is available here*”.

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Then

$\text{length list } 1 : 2 : 3 \quad \rightarrow$
 $S (\text{length list } 2 : 3) \quad \rightarrow$
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$\text{length list } 1 : 2 : 3$	\rightarrow	\perp
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Take the function $\text{length list } a : b = S (\text{length list } b)$.
 $\text{length list } [] = 0$

Then

which has the approximant

$\text{length list } 1 : 2 : 3$	\rightarrow	\perp
$S (\text{length list } 2 : 3)$	\rightarrow	$S (\perp)$
$S (S (\text{length list } 3))$	\rightarrow	$S (S (\perp))$
$S (S (S (\text{length list } [])))$	\rightarrow	
$S (S (S (0)))$	\rightarrow	

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In this case, the output is finite, and the final approximant is the end-result itself.

Sieve of Eratosthenes in Haskell

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primes      = sieve [2..]
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sieve (p:xs) = p : sieve [x | x <- xs, x `mod` p > 0]
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sieve [2..] →
```

```
2:sieve [3..] →
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```
2:3:sieve [5..] →
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```

```
⋮
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⋮		⋮

In this case, the computation is infinite, and so is the output, and there is no final approximant, since the “result” is never reached - \perp is in every approximant.