

Transitive Closure Logic

Infinitary and Cyclic Proof Systems

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Transitive Closure (TC) Logic extends FOL with formulas:

- $(RTC_{x,y} \varphi)(s, t)$
 - φ is a formula
 - x and y are distinct variables (which become bound in φ)
 - s and t are terms

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whose intended meaning is an **infinite disjunction**

$$\begin{aligned} s = t \vee & \varphi[s/x, t/y] \\ & \vee (\exists w_1 . \varphi[s/x, w_1/y] \wedge \varphi[w_1/x, t/y]) \\ & \vee (\exists w_1, w_2 . \varphi[s/x, w_1/y] \wedge \varphi[w_1/x, w_2/y] \wedge \varphi[w_2/x, t/y]) \\ & \vee \dots \end{aligned}$$

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- M is a (standard) first-order model with domain D
- v is a valuation of terms in M :

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$$\wedge M, v[x := a_i, y := a_{i+1}] \models \varphi \quad \text{for all } i < n$$



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- $(RTC_{x, y} \varphi)$ 'denotes' the reflexive, transitive closure of φ :

$$M, v \models (RTC_{x, y} \varphi)(s, t) \Leftrightarrow (v(s), v(t)) \in (\llbracket \varphi(x, y) \rrbracket_{M, v})^*$$

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- It has an intuitive, easy-to-understand semantics
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Theorem (Avron '03)

All finitely inductively defined relations^{} are definable in TC.[†]*

A. Avron, *Transitive Closure and the Mechanization of Mathematics*, 2003.

^{*}as defined in: S. Feferman, *Finitary Inductively Presented Logics*, 1989

[†]with signatures containing a pairing function

Example: Arithmetic

- Take a signature $\Sigma = \{\mathbf{0}, \mathbf{s}\}$ + equality and pairing

$$\mathbf{Nat}(x) \equiv (RTC_{v,w} \mathbf{s} v = w)(\mathbf{0}, x)$$

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$$(RTC_{v,w} \exists n_1, n_2 . v = \langle n_1, n_2 \rangle \wedge w = \langle \mathbf{s} n_1, \mathbf{s} n_2 \rangle)(\langle \mathbf{0}, y \rangle, \langle z, x \rangle)$$

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$\langle \mathbf{0}, y \rangle$

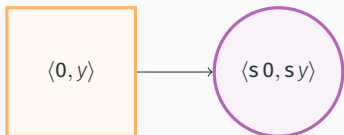
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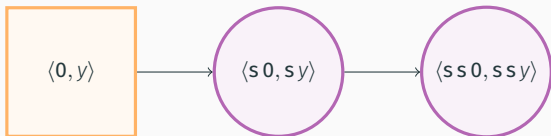
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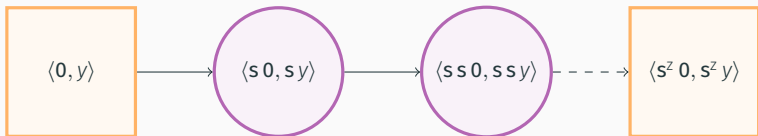
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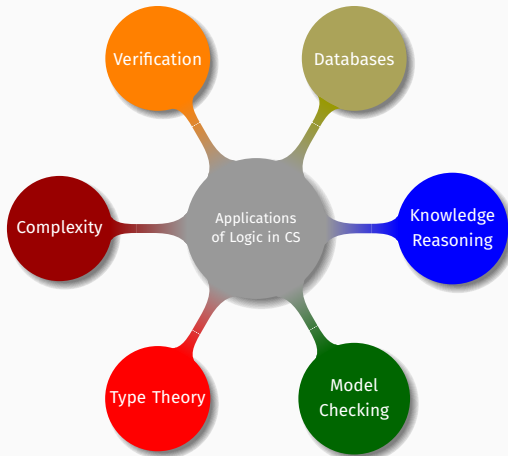
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- The following axioms categorically characterise the natural numbers in **TC**:

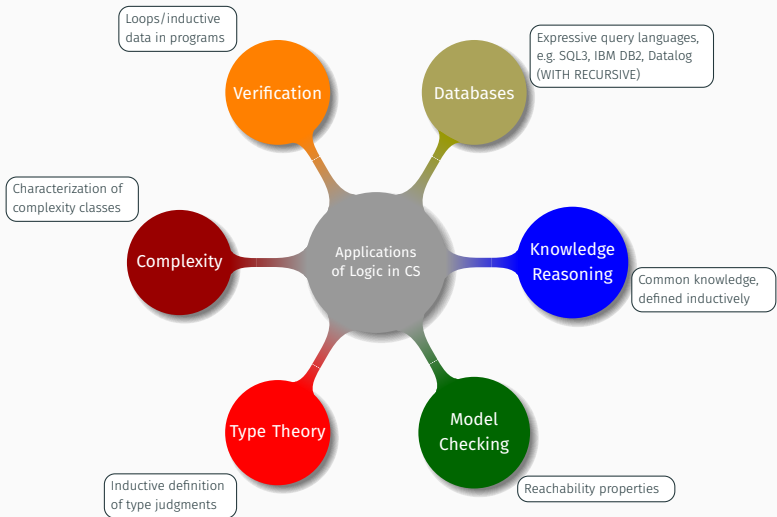
$$\forall x . \mathbf{s} x \neq \mathbf{0}$$

$$\forall x, y . \mathbf{s}(x) = \mathbf{s}(y) \rightarrow x = y$$

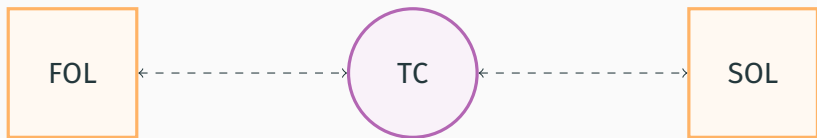
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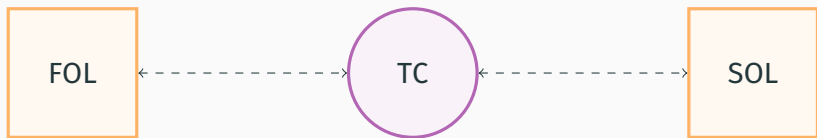


J. Halpern Et Al, *On the Unusual Effectiveness of Logic in Computer Science*, 2001



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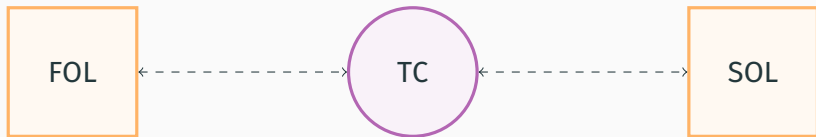




“Everything should be made as simple as possible but not simpler”

—Albert Einstein

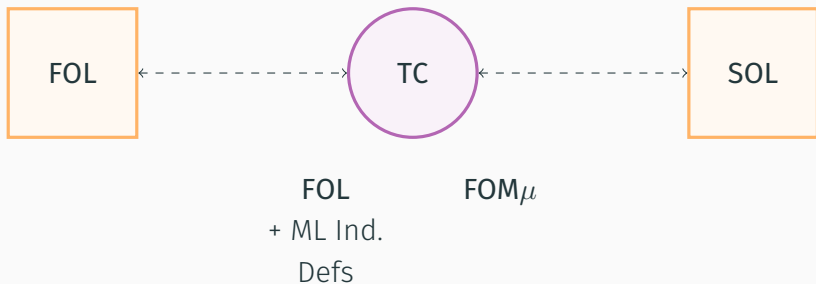
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The transitive closure

$$R^+ = \bigcup_{i \geq 0} R_i, \quad \text{where } R_0 = R$$
$$R_{i+1} = R_i \circ R \quad (i \geq 0)$$

is a **particular** kind of fixed point:

$$R^+ = \mu X. \Psi_R(X)$$

where, for binary relations R and S , we define

$$\Psi_R(S) = R \cup (R \circ S)$$

FOL + Martin-Löf inductive definitions:

- For each predicate symbol P_1, \dots, P_n , we give a set of **productions** of the form:

$$\frac{Q_1(\vec{s}_1) \quad \dots \quad Q_n(\vec{s}_n)}{P_i(\vec{t})}$$

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TC has all possible inductive definitions 'available' using only a finite signature

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FOL_{ID} productions only allow for Horn clauses

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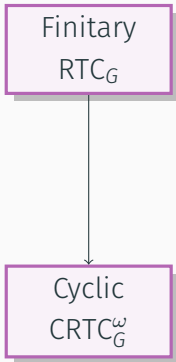
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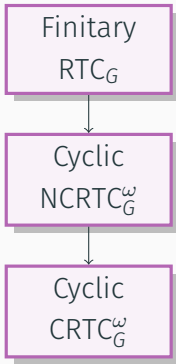


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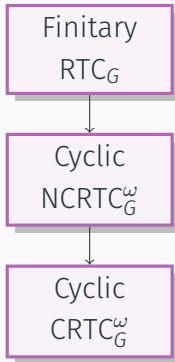


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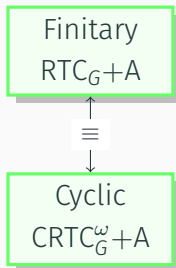
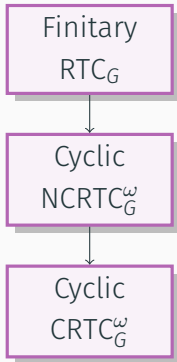
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RTC_G: A Finitary Proof System with 'Explicit' Induction

We add the following rules to Gentzen's sequent calculus for CL with substitution and equality:

reflexivity $\frac{}{\vdash (RTC_{x,y} \varphi)(t, t)}$

step $\frac{\Gamma \vdash \Delta, (RTC_{x,y} \varphi)(s, r) \quad \Gamma \vdash \Delta, \varphi[r/x, t/y]}{\Gamma \vdash \Delta, (RTC_{x,y} \varphi)(s, t)}$

induction $\frac{\Gamma, \psi(x), \varphi(x, y) \vdash \Delta, \psi[y/x]}{\Gamma, \psi[s/x], (RTC_{x,y} \varphi)(s, t) \vdash \Delta, \psi[t/x]}$
 $x \notin \text{fv}(\Gamma, \Delta)$ and $y \notin \text{fv}(\Gamma, \Delta, \psi)$

RTC_G 'captures' TC:

$$\frac{\Gamma \vdash \Delta, (RTC_{x,y} \varphi)(s, t)}{\Gamma \vdash \Delta, (RTC_{x,y} \varphi)(t, s)}$$

$$\frac{\Gamma \vdash \Delta, \varphi[s/x, r/y] \quad \Gamma \vdash \Delta, (RTC_{x,y} \varphi)(r, t)}{\Gamma \vdash \Delta, (RTC_{x,y} \varphi)(s, t)}$$

$$\frac{\Gamma \vdash \Delta, (RTC_{x,y} \varphi)(s, t)}{\Gamma \vdash \Delta, (RTC_{v,w} \varphi[v/x, w/y])(s, t)}$$

$$\frac{\Gamma, \varphi \vdash \Delta, \psi}{\Gamma, (RTC_{x,y} \varphi)(s, t) \vdash \Delta, (RTC_{x,y} \psi)(s, t)}$$

$$\frac{\Gamma, \varphi[s/x] \vdash \Delta}{\Gamma, (RTC_{x,y} \varphi)(s, t) \vdash \Delta, s = t}$$

$$\frac{\Gamma, (RTC_{x,y} \varphi)(s, t) \vdash \Delta}{\Gamma, (RTC_{v,w} (RTC_{x,y} \varphi)(v, w))(s, t) \vdash \Delta}$$

$$\frac{\Gamma \vdash \Delta, (RTC_{x,y} \varphi)(s, t)}{\Gamma \vdash \Delta, s = t, \exists z. (RTC_{x,y} \varphi)(s, z) \wedge \varphi[z/x, t/y]}$$

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- A **TC** Henkin-frame H is a triple $\langle D, I, \mathcal{D} \rangle$
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- RTC formulas are interpreted wrt. frames as follows:

$$H, v \models_{\mathcal{H}} (RTC_{x,y} \varphi)(s, t) \Leftrightarrow$$

for all $A \in \mathcal{D}$, if $v(s) \in A$ and

$$\forall a, b \in D. (a \in A \wedge H, v[x := a, y := b] \models \varphi) \rightarrow b \in A$$

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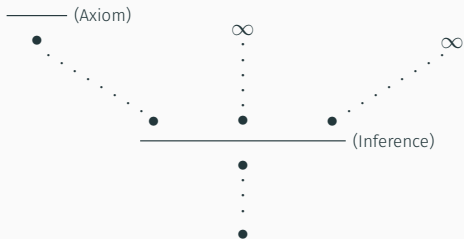
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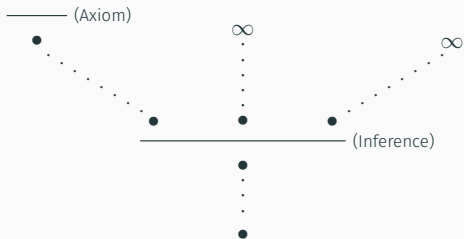
- A **TC** Henkin **structure** is a **TC** Henkin-frame closed under parametric definability, i.e.

$$\{a \in D \mid H, v[x := a] \models \varphi\} \in \mathcal{D} \text{ for all } \varphi, v, \text{ and } H$$

In non-well-founded proof theory we allow infinite height derivations:

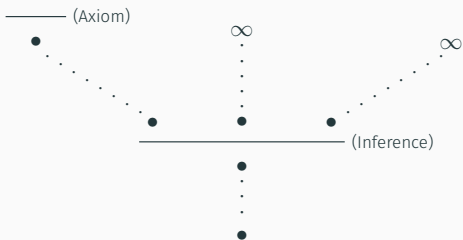


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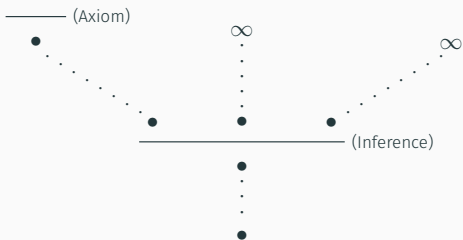
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- We only accept proofs for which every path admits some **infinite** descent
- This is witnessed by tracing terms/formulas corresponding to elements of a well-founded set
- This **global trace condition** is an ω -regular property (i.e. decidable using Büchi automata)

RTC_G^ω : An Infinitary Proof System with ‘Implicit’ Induction

We simply replace the explicit induction rule of RTC_G with:

$$\text{case-split } \frac{\Gamma, s = t \vdash \Delta \quad \Gamma, (RTC_{x,y} \varphi)(s, z), \varphi[z/x, t/y] \vdash \Delta}{\Gamma, (RTC_{x,y} \varphi)(s, t) \vdash \Delta} \text{ (z fresh)}$$

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The trace **progresses** when it traverses the principal formula of a case-split rule.

- Define a **measure** function for RTC -formulas:

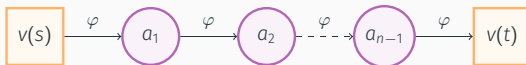
$$\delta_{(RTC_{x,y} \varphi)(s,t)}(M, v) = \begin{cases} \text{minimal no. of } \varphi\text{-steps} \\ \text{from } v(s) \text{ to } v(t) \text{ in } M \end{cases}$$



Soundness of RTC_G^ω

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$$\delta_{(RTC_{v,w} \varphi')(r,u)}(M', v') \leq \delta_{(RTC_{x,y} \varphi)(s,t)}(M, v)$$

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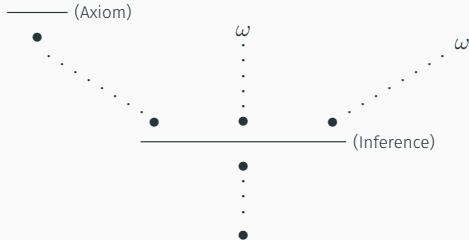
$$\delta_{(RTC_{v,w} \varphi')(r,u)}(M', v') < \delta_{(RTC_{x,y} \varphi)(s,t)}(M, v)$$

- Global trace condition $\Rightarrow n_1 > n_2 > n_3 > \dots$

Obtained using a variation of the standard technique:

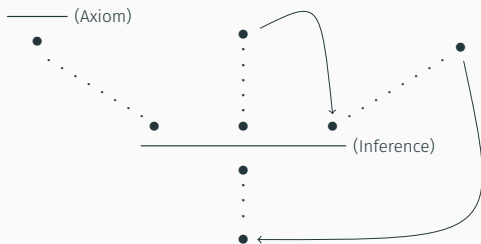
1. Construct an infinite (cut-free) pre-proof via an exhaustive search tree
2. If not a valid proof, then it is possible to construct a counter-model
3. Thus search tree gives a valid proof for every valid sequent

CRTC_G^ω : A Cyclic Subsystem



- Restricting to all and only regular infinite pre-proofs gives an **effective** system

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- Restricting to all and only regular infinite pre-proofs gives an **effective** system
- Regular pre-proofs can be represented as **finite**, possibly **cyclic** graphs

Implicit induction subsumes explicit induction

$$\begin{array}{c}
 \frac{\Gamma, \psi[v/x], (RTC_{x,y} \varphi)(v, w) \vdash \Delta, \psi[w/x]}{\Gamma, \psi[v/x], (RTC_{x,y} \varphi)(v, z) \vdash \Delta, \psi[z/x]} \text{ (Subst)} \quad \frac{\Gamma, \psi, \varphi \vdash \Delta, \psi[y/x]}{\Gamma, \psi[z/x], \varphi[z/x, w/y] \vdash \Delta, \psi[w/x]} \text{ (Subst)} \\
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 \frac{\Gamma, \psi[v/x] \vdash \Delta, \psi[v/x]}{\Gamma, \psi[v/x], v = w \vdash \Delta, \psi[w/x]} \text{ (=L)} \quad \begin{array}{c} \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{array} \\
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NCRTC_G^ω, the subsystem of **non-overlapping** cyclic proofs, is a Henkin-complete

Equivalence Under Arithmetic

Obtain RTC_G+A and $CRTC_G^\omega+A$ by adding the following schemas:

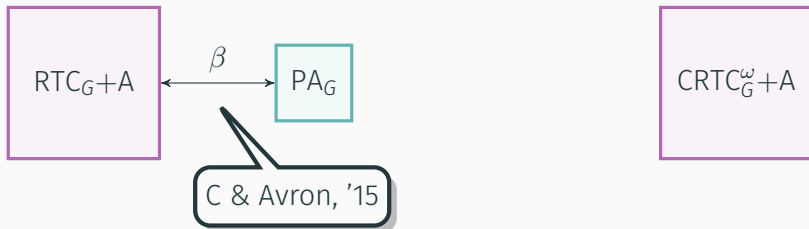
1. $s0 \vdash$
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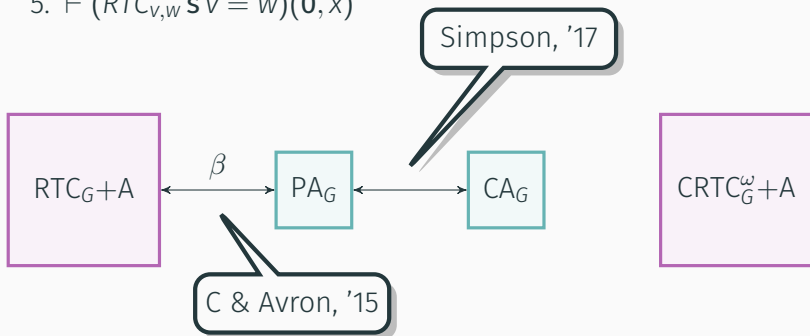
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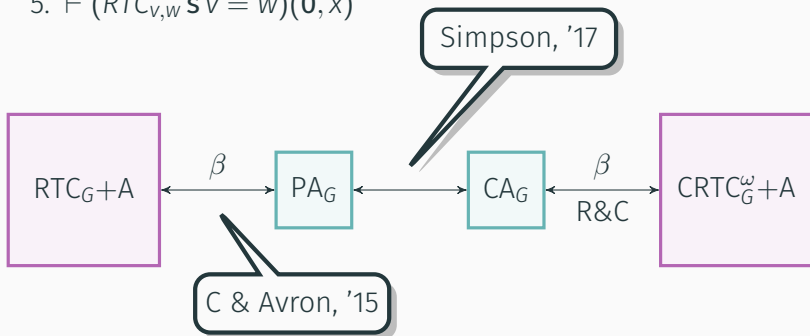
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 - $\mathbf{0}, \mathbf{s}$ -axioms $\vdash_{\text{CLKID}^\omega}$ “2-hydra”



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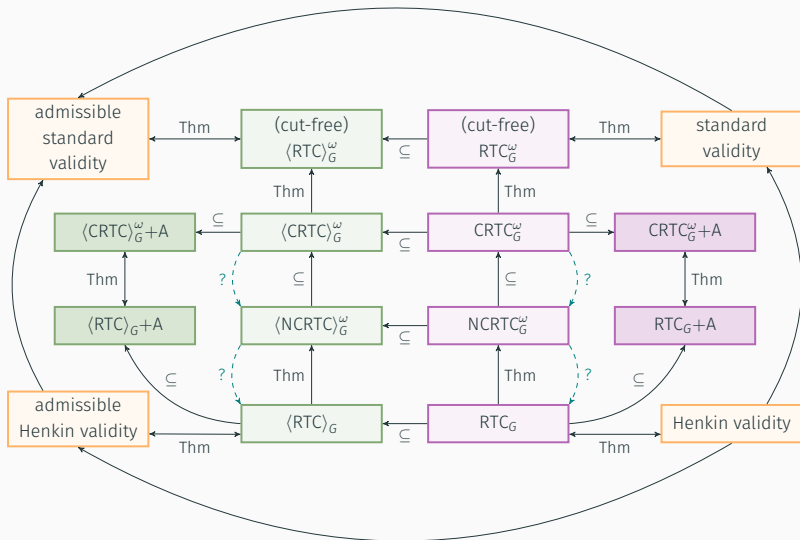
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So this does not serve to show RTC_G and CRTC_G^ω inequivalent

- **TC** has all inductive definitions available

Summary of Results



Future Work

- Resolving the open question of the (in)equivalence of RTC_G , $NCRTC_G^\omega$ and $CRTC_G^\omega$.
- Implementing $CRTC_G^\omega$ and investigating the practicalities of **TC**-logic to support automated inductive reasoning.
- Using the uniformity of **TC**-logic to better study the relationship between implicit and explicit induction.
 - Cuts required in each system
 - Relative complexity of proofs
- A uniform framework for **coinductive** reasoning?

Recall transitive closure as a fixed point:

$$R^+ = \mu X. \Psi_R(X) \qquad \Psi_R(S) = R \cup (R \circ S)$$

The **greatest** fixed point gives the transitive **co**-closure

- Pairs (s, t) in $\nu X. \Psi_R(X)$ are those connected by a possibly infinite number of R -steps
- We can write $(RTC_{x,y}^{\text{op}} \varphi)(s, t)$ to denote that (s, t) is in the reflexive, transitive co-closure of φ
- E.g. The following formula defines possibly infinite lists

$$(RTC_{x,y}^{\text{op}} \exists z. x = \mathbf{cons}(z, y))(v, [])$$

We have the following standard semantics

$$M, v \models (RTC_{x,y}^{\text{op}} \varphi)(s, t) \Leftrightarrow \\ \exists (\vec{a}_i)_{i \geq 0} . \forall i \geq 0 . a_i = v(t) \vee M, v[x := a_i, y := a_{i+1}] \models \varphi$$

We have the following Henkin-semantics

$$H, v \models_{\mathcal{H}} (RTC_{x,y}^{\text{op}} \varphi)(s, t) \Leftrightarrow \\ \text{there exists } A \in \mathcal{D} \text{ such that } v(s) \in A \text{ and} \\ \forall a \in A . \text{ either } a = v(t) \text{ or } \exists b \in A . H, v[x := a, y := b] \models_{\mathcal{H}} \varphi$$