

Complexity Monotone in Conditions and Future Prediction Errors

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Question

$$\log_2 \frac{\mu(y)}{M(y)} \stackrel{+}{\leq} KP(\mu)$$

$$\log_2 \frac{\mu(y|x)}{M(y|x)} \stackrel{+}{\leq} KP(\mu|x) ?$$

μ computable measure

M a priori (universal) semicomputable semimeasure

KP prefix complexity



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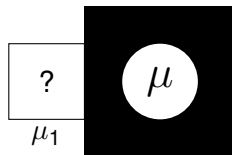
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Sequence



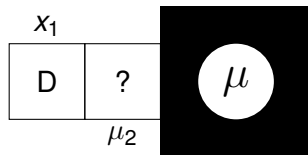
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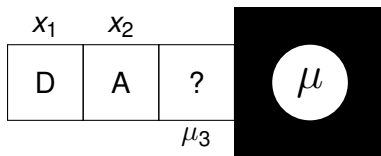
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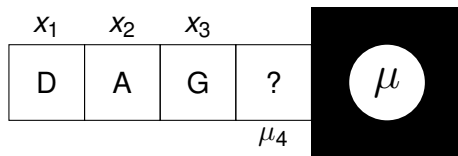
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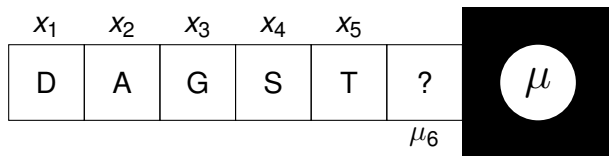
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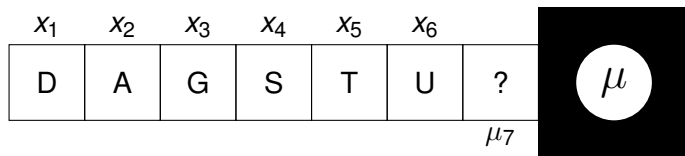
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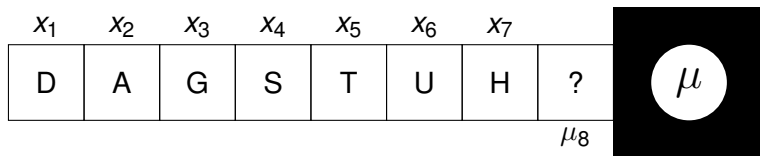
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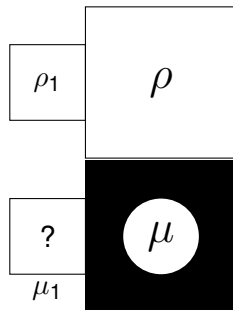
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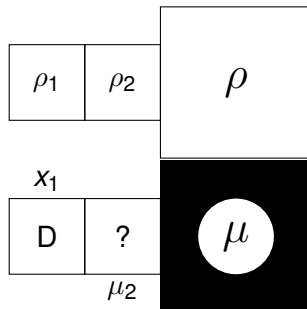
Predictor

Predictor ρ : $x_1, \dots, x_i \mapsto \rho_{i+1}(\cdot) \approx \mu_{i+1}(\cdot)$



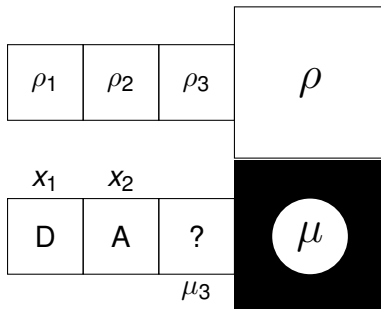
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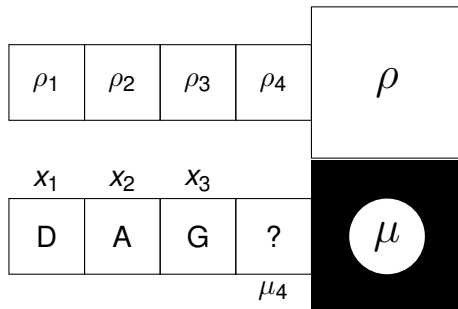
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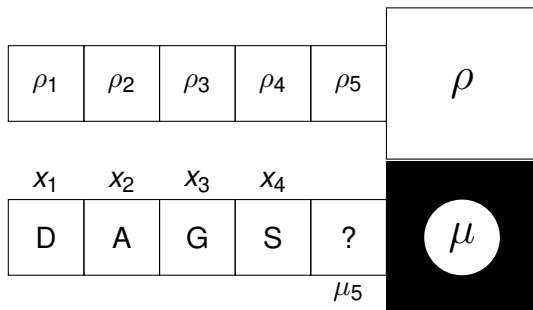
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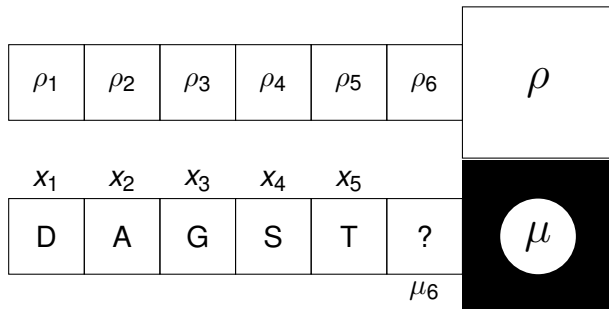
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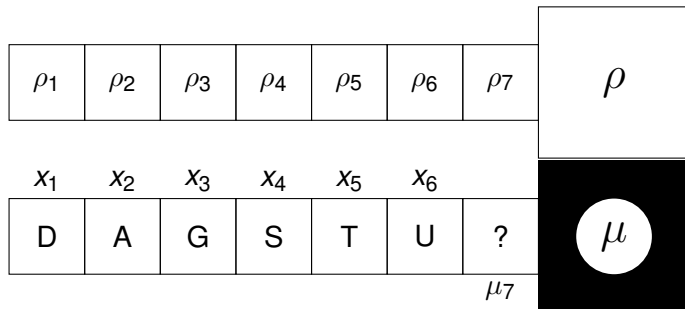
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Predictor

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Quality of prediction

$\rho_i(\cdot) \approx \mu_i(\cdot)$ with high μ -probability:

$$\text{Dist}(\rho, \mu) = \mathbf{E} \sum_{i=1}^{\infty} \text{dist}_{x_1 \dots x_i}(\rho_i, \mu_i) = \sum_{x_1 x_2 \dots} \mu(x_1 x_2 \dots) \sum_{i=1}^{\infty} \text{dist}_{x_1 \dots x_i}(\rho_i, \mu_i)$$

$$\text{dist}_{x_1 \dots x_i}(\rho_i, \mu_i) = \frac{1}{\ln 2} \times$$

$$\sum_{a \in \mathcal{X}} (\rho_i(a) - \mu_i(a))^2 \quad \text{or} \quad \frac{1}{2} \left(\sum_{a \in \mathcal{X}} |\rho_i(a) - \mu_i(a)| \right)^2 \quad \text{or}$$

$$\sum_{a \in \mathcal{X}} \left(\sqrt{\rho_i(a)} - \sqrt{\mu_i(a)} \right)^2 \quad \text{or} \quad \sum_{a \in \mathcal{X}} \mu_i(a) \ln \frac{\mu_i(a)}{\rho_i(a)}$$

$$0 \leq \text{Dist}(\rho, \mu) \leq D_\rho := \mathbf{E} \log_2 \frac{\mu(x_1 x_2 \dots)}{\rho(x_1 x_2 \dots)}$$

Intuitively: (for a deterministic μ)

$D_\rho \sim$ number of prediction errors



Solomonoff prior

$$\rho_i(\cdot) = \frac{M(x_1 \dots x_i \cdot)}{M(x_1 \dots x_i)} \quad M(x) = \sum_{\mu} w_{\mu} \mu(x)$$

M is a Bayes mixture of **all semi-computable semi-measures**.

Theorem (Solomonoff 1964, 1978)

For any computable measure μ

$$\text{Dist}(M, \mu) \leq D_M \stackrel{+}{\leq} KP(\mu)$$

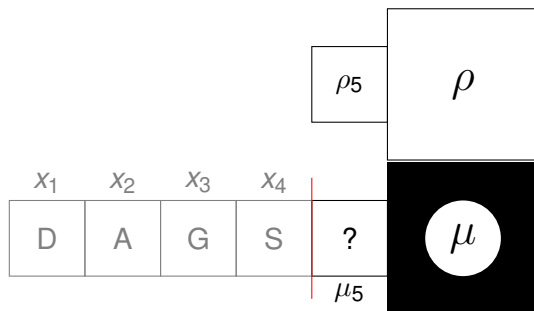
$KP(\mu)$ is Kolmogorov complexity of μ

~ quantity of information in μ

~ the size of the shortest description of μ



Prediction with a priori information

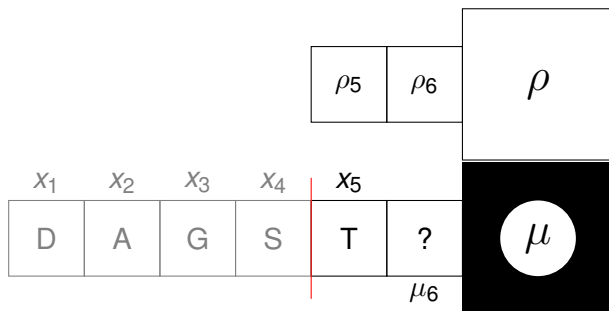


x_1, \dots, x_n are fixed

$$\text{Dist}(\rho, \mu | x_1 \dots x_n) = \mathbf{E}_{x_{n+1}x_{n+2}\dots} \sum_{i=n+1}^{\infty} \text{dist}_{x_1 \dots x_i}(\rho_i, \mu_i)$$



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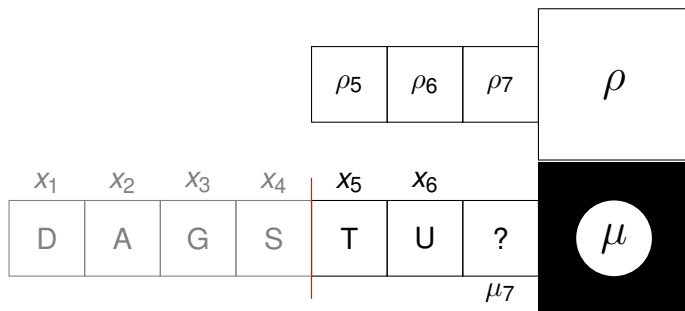


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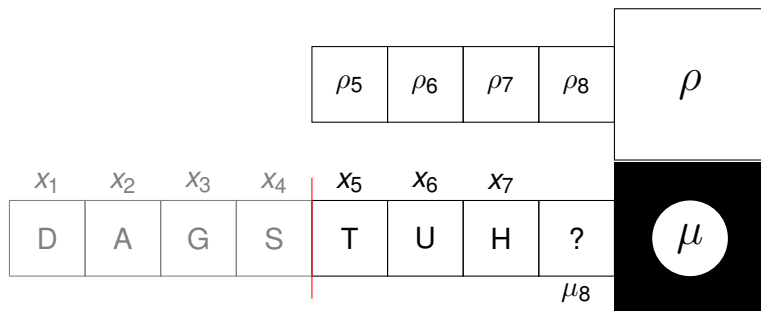


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The problem

$$x = x_1 \dots x_n \quad \text{Dist}(M, \mu|x) \leq D_M(x) := \mathbf{E}_y \log_2 \frac{\mu(y_1 y_2 \dots |x)}{M(y_1 y_2 \dots |x)}$$

For any computable measure μ , for any word x

$$\frac{\mu(y|x)}{M(y|x)} \leq \quad ?$$

We know

$$\log_2 \frac{\mu(y)}{M(y)} \stackrel{+}{\leq} KP(\mu)$$

We want

$$\log_2 \frac{\mu(y|x)}{M(y|x)} \stackrel{+}{\leq} KP(\mu|x)$$

If x contains a lot of information about μ ($KP(\mu|x)$ is small), prediction is easy.



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$KP(\mu|x)$ bound

Theorem

For any computable measure μ and any $x, y \in \mathcal{X}^*$

$$\log_2 \frac{\mu(y|x)}{M(y|x)} \stackrel{+}{\leq} KP(\mu|x) + KP(\ell(x))$$

Corollary

1. $\text{Dist}(M, \mu|x_1 \dots x_n) \stackrel{+}{\leq} KP(\mu|x_1 \dots x_n) + KP(n)$
2. $\text{Dist}(M, \mu) \stackrel{+}{\leq} \min_n \{ \mathbf{E}_{\ell(x)=n} KP(\mu|x) + KP(n) + \frac{2}{\ln 2} n \}$



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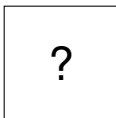
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Example

$$\text{Dist}(M, \mu) \stackrel{+}{\leq} \min_n \{ \mathbf{E}_{\ell(x)=n} KP(\mu|x) + KP(n) + \frac{2}{\ln 2} n \}$$

x_1



“number of errors” $\sim \text{Dist}(M, \mu)$

Solomonoff bound:

$$\text{Dist}(M, \mu) \lesssim KP(\mu) \sim \text{“size of the image”} \approx 10^5$$

New bound:

$$\text{Dist}(M, \mu) \lesssim KP(\mu|x_1) + KP(1) + \frac{2}{\ln 2} \sim \text{“small constant”}$$

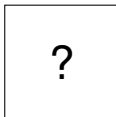


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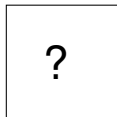
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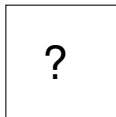
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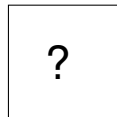
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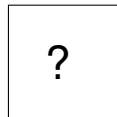
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Analysis of the bound: disinformation

$$\text{Dist}(M, \mu|x) \stackrel{+}{\leq} KP(\mu|x) + KP(\ell(x)) \xrightarrow{\ell(x) \rightarrow \infty} \infty$$

Is it worse than $\text{Dist}(M, \mu) \stackrel{+}{\leq} KP(\mu)$? No!

$$\text{Dist}(M, \mu) = \dots + \sum_{\ell(x)=n} \mu(x) \text{Dist}(M, \mu|x)$$

$\mu(x) \rightarrow 0 \Rightarrow \text{Dist}(M, \mu|x) \rightarrow \infty$ is possible

If x is not typical for μ ($\mu(x) \approx 0$), then we get disinformation



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If x is not typical for μ ($\mu(x) \approx 0$), then we get **disinformation**



How to deal with disinformation

$$\log_2 \frac{\mu(y|x)}{M(y|x)} = \log_2 \frac{\mu(y)}{M(y)} + \log_2 \frac{M(x)}{\mu(x)} \stackrel{+}{\leq} KP(\mu) + \log_2 \frac{M(x)}{\mu(x)}$$

Randomness deficiency: $d_\mu(x) = \log_2 \frac{M(x)}{\mu(x)}$

d_μ is a measure of non-typicalness, $d_\mu(x)$ is small for most x

$d_\mu(x) = \ell(x) - KP(x)$ for uniform μ



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How to deal with disinformation

Theorem (An. Muchnik, A. Shen)

For any computable measure μ and any $x, y \in \mathcal{X}^*$

$$\log_2 \frac{\mu(y|x)}{M(y|x)} \equiv d_\mu(x) - d_\mu(xy) \stackrel{+}{\leq} KP(\mu) + KP(\lceil d_\mu(x) \rceil)$$

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Structure of the bounds

prediction errors \leftarrow information + quantity of disinformation

$$\begin{array}{rclcl}
 \text{Dist}(M, \mu) & \begin{array}{c} + \\ \leq \end{array} & KP(\mu) & & \\
 \text{Dist}(M, \mu|x) & \begin{array}{c} + \\ \leq \end{array} & KP(\mu|x) & + & KP(\ell(x)) \\
 \text{Dist}(M, \mu|x) & \begin{array}{c} + \\ \leq \end{array} & KP(\mu) & + & KP(d_\mu(x)) \\
 \text{Dist}(M, \mu|x) & \begin{array}{c} + \\ \leq \end{array} & KP_*(\mu|x^*) & + & KP(d_\mu(x))
 \end{array}$$



Structure of the bounds

prediction errors	\Leftarrow	information	+	quantity of disinformation
$\text{Dist}(M, \mu)$	$\begin{matrix} + \\ \leq \end{matrix}$	$KP(\mu)$		
$\text{Dist}(M, \mu x)$	$\begin{matrix} + \\ \leq \end{matrix}$	$KP(\mu x)$	+	$KP(\ell(x))$
$\text{Dist}(M, \mu x)$	$\begin{matrix} + \\ \leq \end{matrix}$	$KP(\mu)$	+	$KP(d_\mu(x))$
$\text{Dist}(M, \mu x)$	$\begin{matrix} + \\ \leq \end{matrix}$	$KP_*(\mu x^*)$	+	$KP(d_\mu(x))$



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Structure of the bounds

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$\text{Dist}(M, \mu x)$	\leq	$KP_*(\mu x^*)$	+	$KP(d_\mu(x))$



Prefix complexity **monotone** in conditions

Definition (informal)

$x, y \in \mathcal{X}^*$, U is a universal **twice**-prefix machine, $p \in \{0, 1\}^*$

$$KP_*(y|x^*) = \min\{\ell(p) \mid U(p^*, x^*) = y\}$$

Recall: conditional prefix complexity

$x, y \in \mathcal{X}^*$, U is a universal prefix machine, $p \in \{0, 1\}^*$

$$KP(y|x) = \min\{\ell(p) \mid U(p^*, x) = y\}$$



Prefix complexity **monotone in conditions**

Definition (informal)

$x, y \in \mathcal{X}^*$, U is a universal twice-prefix machine, $p \in \{0, 1\}^*$

$$KP_*(y|x^*) = \min\{\ell(p) \mid U(p^*, x^*) = y\}$$

$$KP_*(y|xz^*) \leq KP_*(y|x^*)$$



$KP_*(\mu|x^*)$ bound

Theorem

For any computable measure μ and any $x, y \in \mathcal{X}^*$

$$\log_2 \frac{\mu(y|x)}{M(y|x)} \stackrel{+}{\leq} KP_*(\mu|x^*) + KP(\lceil d_\mu(x) \rceil)$$

Corollary

$$\text{Dist}(M, \mu|x_1 \dots x_n) \stackrel{+}{\leq} \min_{i \leq n} \{ KP(\mu|x_1 \dots x_i) + KP(i) + KP(d_\mu(x_1 \dots x_i)) \}$$

For μ -typical x , $\text{Dist}(M, \mu|x) \leq KP(\mu|x') + O(\log \ell(x'))$



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Relations between Complexities

$$U(p^*, x^*) = y$$

$$KP_*(y|x^*)$$

$$U(p^*, x) = y$$

prefix

$$U(p, x^*) = y$$

$$U(p^*, x^*) = y^*$$

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plain

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decision

Uspensky, Shen. Relations between Varieties of Kolmogorov Complexities. *Math. Systems Theory*, 1996



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Prefix complexity monotone in conditions

Definition (formal)

$E = \{\langle p, x, y \rangle\}$ is KP_* -correct if

1. $\langle p, x, y_1 \rangle \in E, \langle p, x, y_2 \rangle \in E \Rightarrow y_1 = y_2$;
2. $\langle p, x, y \rangle \in E \Rightarrow \langle p', x', y \rangle \in E \quad \forall p' \sqsupseteq p, x' \sqsupseteq x$;
3. $\langle p, x', y \rangle \in E, \langle p', x, y \rangle \in E, p \sqsubseteq p', x \sqsubseteq x' \Rightarrow \langle p, x, y \rangle \in E$.

Let E be an optimal enumerable KP_* -correct set

$$KP_*(y|x^*) = \min\{\ell(p) \mid \langle p, x, y \rangle \in E\}.$$

