

Prediction with Expert Advice and Game-Theoretic Supermartingales

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Outline

- 1 Framework of Prediction with Expert Advice
- 2 Motivation: Minimal Expected Loss, Calibration, Martingales
- 3 Defensive Forecasting

Sequence Prediction

Sequence of events

$$\omega_1, \omega_2, \omega_3, \dots$$

Outcomes $\omega_t \in \Omega$

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We try to predict the outcomes

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Predictions $\gamma_t \in \Gamma$

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Predictions $\gamma_t \in \Gamma$

The quality of each prediction is measured by a loss function:

$$(\gamma, \omega) \mapsto \lambda(\gamma, \omega) \in \mathbb{R}$$

The quality of the first T predictions: $L_T = \sum_{t=1}^T \lambda(\gamma_t, \omega_t)$

Goal: $L_T \rightarrow \min$

Simple Loss

Two outcomes, two possible predictions

$$\Gamma = \Omega = \{0, 1\}$$

$$\lambda^{\text{simple}}(\gamma, \omega) = 1 - \mathbb{I}_{\{\gamma=\omega\}} = \begin{cases} 0 & \text{if } \gamma = \omega, \\ 1 & \text{if } \gamma \neq \omega \end{cases}$$

$\sum_{t=1}^T \lambda^{\text{simple}}(\gamma_t, \omega_t)$ is the number of errors

Absolute Loss

Two outcomes: $\Omega = \{0, 1\}$

Probabilistic predictions: $\Gamma = \{(\gamma(0), \gamma(1)) \in [0, 1]^2 \mid \gamma(0) + \gamma(1) = 1\}$

$$\lambda^{\text{abs}}(\gamma, \omega) = |\gamma(1) - \omega| = \gamma(0)\lambda^{\text{simple}}(0, \omega) + \gamma(1)\lambda^{\text{simple}}(1, \omega)$$

$\sum_{t=1}^T \lambda^{\text{abs}}(\gamma_t, \omega_t)$ is the expected number of errors

Brier Loss

G. Brier. Verification of Forecasts Expressed in Terms of Probability.
Monthly Weather Review, 1950.

Finitely many outcomes: $\Omega = \{1, \dots, r\}$

Probabilistic predictions:

$$\Gamma = \{\gamma = (\gamma(1), \dots, \gamma(r)) \in [0, 1]^r \mid \sum_{j=1}^r \gamma(j) = 1\}$$

$$\lambda^{\text{Brier}}(\gamma, \omega) = \sum_{j=1}^r (\gamma(j) - \mathbb{I}_{\{\omega=j\}})^2$$

$L_T^{\text{Brier}} \rightarrow \min$ encourages unbiased estimates of the true probabilities

Logarithmic Loss

Finitely many outcomes: $\Omega = \{1, \dots, r\}$

Probabilistic predictions:

$$\Gamma = \{\gamma = (\gamma(1), \dots, \gamma(r)) \in [0, 1]^r \mid \sum_{j=1}^r \gamma(j) = 1\}$$

$$\lambda^{\log}(\gamma, \omega) = -\ln \gamma(\omega)$$

Measures the “quantity of information”.

Logarithmic Loss

P is a probability measure on all sequences $\omega_1\omega_2\omega_3\dots \in \Omega^\infty$

Prediction strategy:

$$\gamma_{t+1} = P(\cdot \mid \omega_1 \dots \omega_t)$$

that is $\gamma_{t+1}(\omega) = \frac{P(\omega_1 \dots \omega_t \omega)}{P(\omega_1 \dots \omega_t)}$

$$L_T = \sum_{t=1}^T \lambda^{\log(\gamma_t, \omega_t)} = -\ln \prod_{t=1}^T \frac{P(\omega_1 \dots \omega_{t-1} \omega_t)}{P(\omega_1 \dots \omega_{t-1})} = -\ln P(\omega_1 \dots \omega_T)$$

$L_T \rightarrow \min \Leftrightarrow$ the likelihood $P(\omega_1 \dots \omega_T) \rightarrow \max$.

Prediction with Expert Advice

At step t	Expert 1	...	Expert K	Learner
Prediction	γ_t^1	...	γ_t^K	
Outcome				

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Prediction with Expert Advice

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Prediction	γ_t^1	...	γ_t^K	γ_t
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$$L_T^k = \sum_{t=1}^T \lambda(\gamma_t^k, \omega_t) \quad L_T = \sum_{t=1}^T \lambda(\gamma_t, \omega_t)$$

Goal: after each step T , for any Expert k ,

$$L_T \leq L_T^k + \text{something small}$$

Loss Bound

Theorem

If λ is an η -mixable loss function, Learner has strategy that guarantees

$$\sum_{t=1}^T \lambda(\gamma_t, \omega_t) \leq \sum_{t=1}^T \lambda(\gamma_t^k, \omega_t) + \frac{\ln K}{\eta}.$$

If λ is a convex loss function, Learner has strategy that guarantees

$$\sum_{t=1}^T \lambda(\gamma_t, \omega_t) \leq \sum_{t=1}^T \lambda(\gamma_t^k, \omega_t) + O(\sqrt{T \ln K}).$$

(Both bounds hold uniformly for all T and for all k .)

Log loss and Brier loss are 1-mixable.

Absolute loss is convex but not mixable. Simple loss is not convex.

$$\lambda \text{ is } \eta\text{-mixable if } \forall K \forall \gamma^k \in \Gamma \forall \mathbf{w}^k \quad \exists \gamma \in \Gamma \forall \omega \quad e^{-\eta \lambda(\gamma, \omega)} \geq \sum_{k=1}^K \mathbf{w}^k e^{-\eta \lambda(\gamma^k, \omega)}.$$

Example: Bayesian Prediction (1)

Logarithmic loss $\lambda^{\log}(\gamma, \omega) = -\ln \gamma(\omega)$

Experts are probability measures P^1, \dots, P^K :

$$\gamma_T^k(\omega) = P^k(\omega \mid \omega_1 \dots \omega_{T-1})$$

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$$P = \sum_{k=1}^K w^k P^k$$

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$$P = \sum_{k=1}^K w^k P^k$$

$$\begin{aligned} \gamma_T(\omega) = P(\omega \mid \omega_1 \dots \omega_{T-1}) &= \frac{\sum_{k=1}^K w^k P^k(\omega_1 \dots \omega_{T-1} \omega)}{\sum_{k=1}^K w^k P^k(\omega_1 \dots \omega_{T-1})} \\ &= \sum_{k=1}^K \frac{w^k \prod_{t=1}^{T-1} \gamma_t^k(\omega_t)}{\sum_{i=1}^K w^i \prod_{t=1}^{T-1} \gamma_t^i(\omega_t)} \gamma_t^k(\omega) \end{aligned}$$

Example: Bayesian Prediction (2)

Logarithmic loss $\lambda^{\log}(\gamma, \omega) = -\ln \gamma(\omega)$

Experts are probability measures P^1, \dots, P^K

Learner's strategy:

$$P = \sum_{k=1}^K \frac{1}{K} P^k$$

Example: Bayesian Prediction (2)

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Experts are probability measures P^1, \dots, P^K

Learner's strategy:

$$P = \sum_{k=1}^K \frac{1}{K} P^k$$

Then for any $\omega_1 \dots \omega_T$

$$P(\omega_1 \dots \omega_T) \geq \frac{1}{K} P_k(\omega_1 \dots \omega_T)$$

$$L_T = -\ln P(\omega_1 \dots \omega_T) \leq -\ln P_k(\omega_1 \dots \omega_T) + \ln K = L_T^k + \ln K$$

Counterexample: Simple Game of Prediction

$$\omega, \gamma \in \{0, 1\}$$

$$\lambda^{\text{simple}}(\gamma, \omega) = 1 - \mathbb{I}_{\{\gamma=\omega\}} = \begin{cases} 0 & \text{if } \gamma = \omega, \\ 1 & \text{if } \gamma \neq \omega \end{cases}$$

Experts:

$$\gamma_t^1 = 0, \gamma_t^2 = 1 \quad \forall t$$

Outcome:

$$\omega_t = 1 - \gamma_t$$

$$L_T = T, L_T^1 + L_T^2 = T \quad \Rightarrow \quad L_T \geq \min_k L_T^k + T/2$$

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Minimal Expected Loss

At step t , ω_t is sampled from a distribution P_t
and Learner knows the distributions P_t

Learner's prediction: $\gamma_t = \arg \min_{\gamma \in \Gamma} \mathbf{E}_t \lambda(\gamma, \omega_t)$

Then

$$\sum_{t=1}^T \mathbf{E}_t \lambda(\gamma_t, \omega_t) \leq \sum_{t=1}^T \mathbf{E}_t \lambda(\gamma_t^k, \omega_t)$$

Minimal Expected Loss

At step t , ω_t is sampled from a distribution P_t and Learner knows the distributions P_t

Learner's prediction: $\gamma_t = \arg \min_{\gamma \in \Gamma} \mathbf{E}_t \lambda(\gamma, \omega_t)$

Then with high probability

$$\begin{aligned} \sum_{t=1}^T \lambda(\gamma_t, \omega_t) + O(\sqrt{T}) \\ \parallel \\ \sum_{t=1}^T \mathbf{E}_t \lambda(\gamma_t, \omega_t) &\leq \sum_{t=1}^T \mathbf{E}_t \lambda(\gamma_t^k, \omega_t) \\ &\parallel \\ &\sum_{t=1}^T \lambda(\gamma_t^k, \omega_t) + O(\sqrt{T}) \end{aligned}$$

Calibration

Dawid, 1982

Sequence of outcomes $\omega_t \in \{0, 1\}$:

$$\omega_1, \omega_2, \omega_3, \dots$$

We consider probability forecasts $p_t \in [0, 1]$:

$$p_1, \omega_1, p_2, \omega_2, p_3, \omega_3, \dots$$

Forecasts are **well-calibrated** if for any $p \in [0, 1]$

$$\frac{\sum_{t: p_t=p} \omega_t}{\#\{t: p_t = p\}} \rightarrow p$$

“Ignorant” Calibration

Theorem (Foster, Vohra, 1998)

There is a randomised strategy constructing p_t given $\omega_1 \dots \omega_{t-1}$ s.t. for any $\omega_1 \omega_2 \dots$ the forecasts p_t are well-calibrated with high probability

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Generally:

P is a distribution on $\vec{\omega} \in \Omega^\infty$, $\text{Test}(P, \vec{\omega}) \in \{\text{accept}, \text{reject}\}$

Theorem (Sandroni, 2003)

If Test accepts $\vec{\omega}$ sampled from P with P -probability $1 - \epsilon$ for any P then there is a randomised strategy that constructs P on-line given $\vec{\omega}$ s.t. $\text{Test}(P, \vec{\omega})$ accepts with probability $1 - \epsilon$.

Informal Idea: “Ignorant” Expected Loss

Given $\omega_1, \omega_2, \dots$ and Expert's γ^k
we want to construct a distribution P s.t.

$$\mathbf{E} \sum_{t=1}^T \lambda(\gamma_t^P, \omega_t) = \sum_{t=1}^T \lambda(\gamma_t^P, \omega_t) + O(\sqrt{T})$$

and

$$\mathbf{E} \sum_{t=1}^T \lambda(\gamma_t^k, \omega_t) = \sum_{t=1}^T \lambda(\gamma_t^k, \omega_t) + O(\sqrt{T})$$

where

$$\gamma_t^P = \arg \min_{\gamma \in \Gamma} \mathbf{E}_t \lambda(\gamma, \omega_t)$$

Martingales

$\omega_1 \omega_2 \dots$ sampled from some distribution P

$$S_t = S(\omega_1, \dots, \omega_t)$$

S is a martingale if

$$\mathbf{E}[S_t \mid \omega_1, \dots, \omega_{t-1}] = S_{t-1}$$

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Theorem (Ville, 1939)

If $P(A) < \epsilon$ then a supermartingale S exists s.t.

$\lim_{t \rightarrow \infty} S(\omega_1, \dots, \omega_t) \geq 1/\epsilon$ for $\vec{\omega} \in A$.

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Sandroni theorem test: $P\{\vec{\omega} \mid \text{Test}(P, \omega) = \text{reject}\} < \epsilon$

(i.e., uniformly $P(A_P) \leq \epsilon$)

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Game-Theoretic Supermartingales

Informally:

S_t is player's capital after round t

ω_t is outcome of round t

distribution P is the rules of the game

If player has a uniform strategy for all P then S_t is a function of P , $\vec{\omega}$ and also player's additional knowledge

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If player has a uniform strategy for all P then S_t is a function of P , $\vec{\omega}$ and also player's additional knowledge

$\omega_1, \omega_2, \dots \in \Omega$

π_1, π_2, \dots are distributions on Ω

S is a **game-theoretic supermartingale** if for any π

$$\int_{\Omega} S(\mathbf{e}_1, \pi_1, \omega_1, \dots, \mathbf{e}_T, \pi, \omega) \pi(d\omega) \leq S(\mathbf{e}_1, \pi_1, \omega_1, \dots, \mathbf{e}_{T-1}, \pi_{T-1}, \omega_{T-1})$$

Levin's Lemma

Lemma (Levin, 1976)

If $s(\pi, \omega)$ is continuous in π and for some C

$$\forall \pi \quad \int_{\Omega} s(\pi, \omega) \pi(d\omega) \leq C$$

then there exists π s.t.

$$\forall \omega \quad s(\pi, \omega) \leq C$$

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If $s(\pi, \omega)$ is continuous in π and for some C

$$\forall \pi \quad \int_{\Omega} s(\pi, \omega) \pi(d\omega) \leq C$$

then there exists π s.t.

$$\forall \omega \quad s(\pi, \omega) \leq C$$

Proof idea: Consider $\phi(\pi', \pi) = \int_{\Omega} s(\pi, \omega) \pi'(d\omega)$

$$\begin{aligned} s(\pi, \omega_0) &= \int_{\Omega} s(\pi, \omega) \delta_{\omega_0}(d\omega) = \phi(\delta_{\omega_0}, \pi) \\ &\leq \max_{\pi'} \phi(\pi', \pi) = \min_{\pi} \max_{\pi'} \phi(\pi', \pi) = \max_{\pi'} \min_{\pi} \phi(\pi', \pi) \\ &\leq \max_{\pi'} \phi(\pi', \pi') \leq C \end{aligned}$$

Supermartingales for PEA: Mixable Games

If $\lambda(\gamma, \omega)$ is η -mixable then for any distribution π and for any $\gamma \in \Gamma$

$$\int_{\Omega} e^{\eta(\lambda(\pi, \omega) - \lambda(\gamma, \omega))} \pi(d\omega) \leq 1$$

where $\lambda(\pi, \omega)$ is a **proper** loss function: for any π and any $\gamma \in \Gamma$

$$\int_{\Omega} \lambda(\pi, \omega) \pi(d\omega) \leq \int_{\Omega} \lambda(\gamma, \omega) \pi(d\omega)$$

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where $\lambda(\pi, \omega)$ is a proper loss function: for any π and any $\gamma \in \Gamma$

$$\int_{\Omega} \lambda(\pi, \omega) \pi(d\omega) \leq \int_{\Omega} \lambda(\gamma, \omega) \pi(d\omega)$$

$$S_T = \sum_{k=1}^K \left(\frac{1}{K} \prod_{t=1}^T e^{\eta(\lambda(\pi_t, \omega_t) - \lambda(\gamma_t^k, \omega_t))} \right)$$

is a supermartingale.

Choosing π_t by Levin's lemma, we can guarantee that $S_T \leq 1$ for all T .

Supermartingales for PEA: Logarithmic Loss

Consider $\lambda^{\log}(\gamma, \omega) = -\ln \gamma(\omega)$ (which is 1-mixable)

For any distribution π and for any $\gamma \in \Gamma$

$$\begin{aligned} \int_{\Omega} e^{\lambda^{\log}(\pi, \omega) - \lambda^{\log}(\gamma, \omega)} \pi(d\omega) \\ = \sum_{\omega \in \Omega} e^{-\ln \pi(\omega) + \ln \gamma(\omega)} \pi(\omega) = \sum_{\omega \in \Omega} \frac{\gamma(\omega)}{\pi(\omega)} \pi(\omega) = 1 \end{aligned}$$

$$S_T = \sum_{k=1}^K \frac{1}{K} \prod_{t=1}^T \frac{\gamma_t^k(\omega_t)}{\pi_t(\omega_t)} \leq 1$$

Supermartingales for PEA: Convex Games

If $\lambda(\gamma, \omega)$ is convex then

for any distribution π , for any $\gamma \in \Gamma$, for any $\eta > 0$,

$$\int_{\Omega} e^{\eta(\lambda(\pi, \omega) - \lambda(\gamma, \omega)) - \eta^2/2} \pi(d\omega) \leq 1$$

where $\lambda(\pi, \omega)$ is a proper loss (multi-)function: for any π and any $\gamma \in \Gamma$

$$\int_{\Omega} \lambda(\pi, \omega) \pi(d\omega) \leq \int_{\Omega} \lambda(\gamma, \omega) \pi(d\omega)$$

$$S_T = \sum_{k=1}^K \left(\frac{1}{K} \prod_{t=1}^T e^{\eta(\lambda(\pi_t, \omega_t) - \lambda(\gamma_t^k, \omega_t)) - \eta^2/2} \right)$$

is a supermartingale.

Letting $\eta = O(1/\sqrt{T})$ and choosing π_t by Levin's lemma, we can guarantee that $S_T \leq 1$ for all T .

Laws of Probability (1)

Probability law: $P(A_P)$ is small for any P

Game-theoretic supermartingales correspond to probability laws

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Supermartingale for convex games: Hoeffding inequality

If $X \in [-1, 1]$ then

$$\mathbf{E}e^{\eta X} \leq e^{\eta \mathbf{E}X + \eta^2/2}$$

For independent $X_1, \dots, X_N \in [-1, 1]$

$$P \left[\frac{1}{N} \left| \sum_{n=1}^N (X_n - \mathbf{E}X_n) \right| > \epsilon \right] \leq 2e^{-\epsilon^2 N/2}$$

Laws of Probability (2)

Supermartingale for mixable games:

λ is proper η -mixable loss function,

P is any distribution, $\pi_t = P(\omega \mid \omega_1 \dots \omega_{t-1})$,

P^1, \dots, P^K are any distributions and $\pi_t^k = P^k(\omega \mid \omega_1 \dots \omega_{t-1})$

$$P \left\{ \vec{\omega} \mid \forall T \forall k = 1, \dots, K \sum_{t=1}^T \lambda(\pi_t, \omega_t) \geq \sum_{t=1}^T \lambda(\pi_t^k, \omega_t) + \frac{1}{\eta} \ln \frac{K}{\delta} \right\} \leq \delta$$

Special case: $\lambda^{\log}(\pi, \omega) = -\ln \pi(\omega)$

$$P \left\{ \vec{\omega} \mid \forall T \forall k = 1, \dots, K \frac{P^k(\omega_1 \dots \omega_T)}{P(\omega_1 \dots \omega_T)} \geq \frac{\delta}{K} \right\} \leq \delta$$

References

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These slides:

pareto.cs.rhul.ac.uk/~chernov/PEAmartingales.pdf