

# **The Capacitated Cluster Edit Problem**

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# Overview

- The Cluster Edit problem
- Aspects of desired solutions
- **The Capacitated versions**
- Effect of parameterization
- Experiments & concluding remarks

# Cluster Edit

- ***Cluster graph***: graph whose connected components are cliques.
  - AKA ***transitive graph***
- ***Edge-edit*** operations
  - delete an edge
  - add an edge
- The Cluster Edit problem:
  - Given**: a simple undirected graph  $G$ ; parameter  $k$
  - Question**: can we perform  $k$  edge-edit operations to obtain a cluster graph?

# Cluster Edit

- **NP-Complete** (many proofs!)
  - [Krivanek-Moravek, 1986]
  - [Bansal et al., 2004]
  - [Shamir et al., 2004]
  - [Komusiewicz-Uhlmann, 2012]
- **Fixed-Parameter Tractable**, due to a sequence of algorithms, including:
  - [Gramm, Guo, Huffner & Niedermier, 2005]
  - [Bocker, Briesemeister, Bui & Truss, 2009]
  - [Böcker, 2011]
- **Linear Kernel**
  - [Guo, 2009]
  - [Chen & Meng, 2012] ( $2k$ -kernel)

# Sources of difficulty

- **Sizes and number** of clusters unknown
- Existing fixed-parameter algorithms run in  $O^*(c^k)$ .  
( $c = 1.618..$  in the most recent algorithm of Böcker.)
- Yet, the number of edge-edit operations could be larger than  $n$
- Exact  $O^*(c^n)$  algorithms lag behind ...
- Approximation might help. However:
  - Constant-factor approximation is known only when the number of clusters is 2 [Shamir et al., 2004]

# Why Cluster Edit?

- Accurate clustering
- Unsupervised clustering
- Examples:
  - vertices of graph may correspond to protein sequences while an edge means “common domain”
  - graph may correspond to a social network where people may be clustered according to “common interests” etc...
- Best used on nearly clustered data

# How Frequent are False Positives/Negatives?

- Frequency of errors could be low in general
- Our assumption: errors per vertex even less frequent
- Introduce new parameters: the vertex capacities
  - **Add capacity**: amount of edges that can be added
  - **Delete capacity**: amount of edges that can be deleted
- Similar work appeared recently in a paper by Komusiewicz & Uhlmann, who assume a bound on the total number of edge-edit operations per vertex.
- In some applications, it is very important to distinguish between the expected number of false positives and that of false negatives.

# How Small can a Cluster be?

- Obviously, trivial clusters are not significant in real applications
- In general, clusters cannot be too small
- Consequently, add another parameter!

***s = lower bound on cluster size***

- An application-specific threshold below which cluster size is not acceptable
- Ranges between a small constant and a fraction of  $n$



# Capacitated Cluster Edit

- Given: a graph  $G=(V,E)$ ; parameters  $a,d,s$  and  $k$
- Question: can  $G$  be transformed into a cluster graph so that:
  - At most  $a$  edge additions allowed per vertex
  - At most  $d$  edge deletions allowed per vertex
  - Each (resulting) cluster has at least  $s$  elements
  - At most  $k$  total edge-edits permitted
- We refer to this problem by  $(a,d,s,k)$ -Cluster Edit, or  $(a,d,s,k)$ -CE
- In general,  $(a,d,s,k)$ -CE is NP-hard
  - the original formulation is a special case: set  $s = 1$  and  $a = d = k$

## (a,d,s,k) Cluster Edit

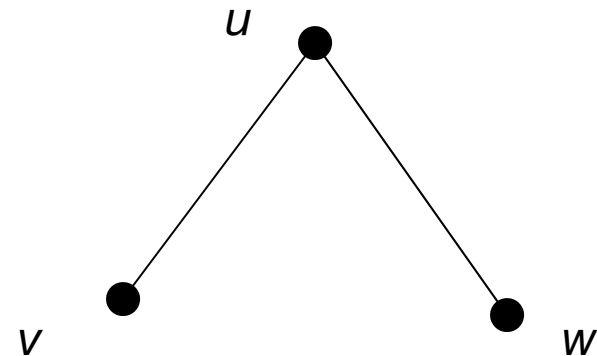
- When  $a=d=c$  we refer to problem as (c,s,k)-CE
- Capacities change during search. We assume the input is given with two capacity functions:
  - $a: V \rightarrow \{0, \dots, c\}$  gives the number of edges that can be added per vertex
  - $d: V \rightarrow \{0, \dots, c\}$  gives the number of edges that can be deleted per vertex
- In this formulation,  $a, d \leq c$  and, for all  $v$  in  $V(G)$ ,
  - $a(v) \leq a$  and  $d(v) \leq d$

## (a,d,s,k) Cluster edit

- Problem can be modified further by introducing **yet another parameter**:
  - the number of outliers
- Outliers may be identified during search:
  - Whenever a vertex has more/less than we can afford deleting/adding

# Cluster Edit Terminology

- Permanent edge: not to be deleted
  - An added edge is implicitly permanent
- Forbidden edge: not to be added
  - Deleted edges are forbidden
- To cliquify a subgraph  $H$  is to make  $G[H]$  a clique by adding the missing edges
- Permanent clique:
  - all edges in clique are permanent
- Conflict triple
  - Induced path of length two
  - Edge-edit operations are needed as long as such paths exist



# Special Cases

- $(a,0,n,k)$ -Cluster Edit: Solvable in polynomial time
- $(0,k,n,k)$ -Cluster Edit: NP-Hard, aka. Cluster Deletion
  - Solvable in  $O^*(1.415^k)$  time [Böcker-Damaschke, 2011]
- $(0,d,n,k)$ - Cluster Edit
  - Solvable in  $O^*(1.415^k)$  time (run-time is better when  $s$  is small)
- $(a,d,s,k)$ -Cluster Edit where  $a+d \geq 4$ : NP-hard [Komusiewicz-Uhlmann, 2012]
- $(1,1,s,k)$ -CE and  $(0,2,s,k)$ -CE: solvable in polynomial-time (to appear!)

# $(0,2,s,k)$ Cluster Edit

- If two adjacent vertices  $u$  and  $v$  have three common neighbors, then
  - $uv$  becomes permanent!
- Any clique of size 5 or more becomes permanent
- If  $\text{degree}(v) > 5$  then every “permanent” neighbor  $u$  of  $v$  must have at least 3 common neighbors with  $v$ . Otherwise, delete edge  $uv$
- If  $\text{degree}(v) > 5$  then
  - $N[v]$  becomes a cluster (thus deleted)
- What if  $s = 6$ ?
  - Then no vertex can be of degree  $< 5$
  - And a vertex of degree-5 cannot lose any more edges, so its closed neighborhood becomes a cluster
- In general, we can deal with vertices of degrees 4 or 5. And  $(0,k,n,k)$ -CE is solvable in polynomial-time on graphs of degree  $< 4$  [Komusiewicz-Uhlmann, 2012]

## $(1,1,s,k)$ Cluster edit

- Every clique of size 3 or more becomes permanent
- If two adjacent vertices have a common neighbor, then their edge becomes permanent
- If two non-adjacent vertices share exactly one common neighbor and one of them is of degree  $> 2$ , then their edge is forbidden
- If vertex  $u$  has only one neighbor  $v$  in a clique of size  $> 2$ , then delete the edge  $uv$

# $(1,1,s,k)$ Cluster edit

- Connected components of the resulting instance are either cliques or triangle-free
  - every  $K_3$  is permanent and every vertex connected to two elements of a clique becomes part of the same (permanent clique),
- Any reduced instance  $(G,1,1,s,k)$  has maximum degree three.
- It follows that  $(1,1,5,k)$ -Cluster Edit is automatically solved by reduction rules:
  - If a component of the reduced instance is not a clique, then No solution!
- Moreover, setting  $s = 4$  yields a simple poly-time algorithm:
  - Only  $C_4$  can lead to a clique of size 4 in only one way.
  - Note: cannot cliquify the neighborhood of a degree-three vertex.



# General Problem Reduction

# Reduction Procedures

- Preprocessing strategies that can be applied at any point during the search algorithm
- Reductions are based on rules, each of the form:  $\langle \text{condition}, \text{action} \rangle$
- If a reduction is not possible, then we have a no instance

# Reduction Rule 1

- If there is a vertex  $v$  such that  $d(v) = 0$ , then
  - every edge incident on  $v$  becomes permanent
  - consequently: ***Cliquify***  $N(v)$

## Reduction Rule 2

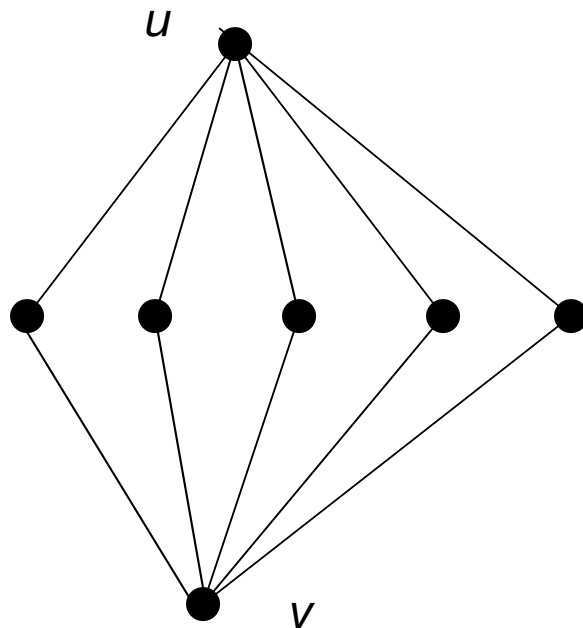
- If a vertex  $v$  satisfies  $a(v) = 0$ , then
  - every non-edge incident on  $v$  becomes forbidden.
- Moreover if  $a(v) = d(v) = 0$ , then:
  - all edges between  $N(v)$  and  $V \setminus N[v]$  are deleted
  - Consequently: cluster containing  $v$  is completely identified, thus ***deleted***

## Reduction Rule 3

- If edge  $uv$  is permanent while edge  $uw$  is forbidden, then  $vw$  is forbidden
- If edges  $uv$  and  $uw$  are permanent, then edge  $vw$  is permanent

## Reduction Rule 4

- If two non-adjacent vertices  $u$  &  $v$  have  $d(u) + d(v) + 1$  common neighbors (or just  $2d+1$ ), then
  - Add edge  $uv$



*If  $d = 2$ , add  $uv$*

Same holds if two adjacent vertices have  $2d$  common neighbors ( $uv$  becomes a permanent edge)

## Reduction Rule 6

If there is a vertex  $v$  satisfying

$$\deg(v) < s - a(v) - 1, \text{ then}$$

No instance (or  $v$  is an outlier!)

In particular, if  $\deg(v) < s - a - 1$ , then No

# Reduction Rule 7

- If two non-adjacent vertices  $u$  and  $v$  have less than  $s - 2a$  common neighbors, then
  - set edge  $uv$  as forbidden
- Soundness: for  $u$  and  $v$  to belong to the same cluster, they must have at least  $s-2$  common neighbors. After adding  $uv$ , the maximum number of common neighbors we can add is  $2a - 2$  ( $a-1$  edges between  $u$  and  $N(v)$  and vice versa). The total number of common neighbors after adding all possible edges remains less than  $s-2$  ( $= s-2a+2a-2$ ).
- If  $u$  and  $v$  are adjacent and have  $< s - 2a - 2$  common neighbors, then
  - delete edge  $uv$



# Reduced Instances

- By Rules 4 and 7, any two vertices  $u, v$  that are at distance two from each other satisfy:
  - $s - 2a \leq |N(u) \cap N(v)| \leq 2d$
- What if  $s - 2a > 2d$ ? (or  $s > 2(a+d)$ )
- Two cases:
  - No two non-adjacent vertices have common neighbors
  - No instance

# Complexity of $(a,d,s,k)$ -Cluster Edit

- Theorem: If  $s > 2(a+d)$ , then  $(a,d,s,k)$  is solvable in polynomial-time
- Proof:
  - When  $s > 2(a + d)$ , every reduced instance is a cluster graph.
- Thus, problem is hard only when the percentage of error is a (relatively) large fraction of the minimum cluster size!
  - When  $a=d$ , each of  $a$  and  $d$  is larger than  $s/4$
  - In general  $a+d \geq s/2$

# Further Reduction

Large Cliques and Large Neighborhoods

# Large Cliques

- If a clique  $C$  is of size  $\geq 2d + 2$  then  $C$  is permanent
  - Any two elements of  $C$  have at least  $2d$  common neighbors, so (by Rule 4) they belong to the same cluster.
- Reduction Rule 8: If a vertex  $v$  has more than  $d$  neighbors in a permanent clique  $C$ , then ***join***  $v$  to  $C$
- Reduction Rule 9: If  $v$  has less than  $|C| - d$  neighbors in a permanent clique  $C$ , then ***detach***  $v$  from  $C$

## Reduction Rule 10

- In a reduced instance, if a vertex  $v$  has **more** than  $2(a+d)$  neighbors, then:

$N[v]$  is a cluster  $\rightarrow$  cliquify and delete  $N[v]$

- Soundness:
  - Any vertex  $u$  is either a neighbor of  $v$  or has  $< 2d + 1$  common neighbors with  $v$ . In this latter case,  $v$  has more than  $2a$  vertices that are not common with  $u$ . Edge  $uv$  would then be forbidden by Rule 7.

## $(a,d,s,k)$ -Cluster Edit Kernel

- Using the recent kernelization of Chen & Meng, we assume given graph has at most  $2k$  vertices
- How about number of edges?

# $(a,d,s,k)$ -Cluster Edit Kernel

- **Theorem:** There is a reduction algorithm that takes an arbitrary instance of  $(a,d,s,k)$ -Cluster Edit and either determines that no solution exists or produces an equivalent instance whose size is bounded by  $2(a+d)k$
- Simply:
  - By Rule 10, each remaining vertex has degree  $\leq 2(a+d)$
  - Total number of edges  $\leq 2k(2(a+d)/2)$ .

# Preliminary Experiments for $(a,d,n,k)$ -CE

- We used a simple cluster-graph generator followed by random selection of edges to delete/add.
- On graphs of size  $\sim 1000$  or more, with  $k > 140$  and  $a = d = 3$ , an early version of  $(a,d,n,k)$  was much faster than most recent CE algorithm ( $> 400$  hours to  $\sim 1$  hour on some graphs of size 1000) [A. Ghrayeb, 2011].
- Using the reduction procedure described in this talk, and a few more reduction rules, many instances of the capacitated version can be solved during the preprocessing phase.
- More work is currently underway to implement and test reduction procedures when the parameter  $s$  is set.



# Summary

- Adding the parameters **a**, **d** and **s** allowed us to solve Cluster Edit in polynomial time when  $s > 2(a+d)$ , which is a common case.
- When  $a+d$  is not small (with respect to  $s$ ), we obtained a linear-size kernel.
- When  $s \leq 2(a+d)$ , setting  $s$  to be a (reasonably) large constant should yield improved fixed-parameter algorithms.

# Lessons Learned

- General intractable problems are often
  - **Easy** to define
  - **Hard** to solve
  - **Hard** to apply
- Application-driven parameterizations could achieve practicality in two ways:
  - **Better problem models**
  - **Faster algorithmic solutions**